

Chapter 30: Finite-Difference: Parabolic Equation

①

Parabolic (Heat) equation

$$\frac{\partial T}{\partial t} = k \frac{\partial^2 T}{\partial x^2}$$

T : Temperature $T(x, t)$

t : Time

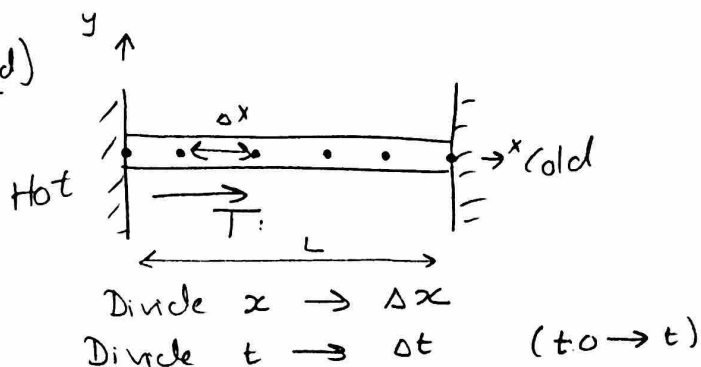
x : space (location)

k : constant.

* Finite Difference method (Explicit method)

2nd derivative using centered
Finite difference approximation

$$\frac{\partial^2 T}{\partial x^2} = \frac{T_{i+1,j} - 2T_{i,j} + T_{i-1,j}}{(\Delta x)^2}$$



and 1st derivative using Forward
finite difference approximations

$$\frac{\partial T}{\partial t} = \frac{T_{i,j+1} - T_{i,j}}{\Delta t}$$

Δx : step size in x
 Δt : step size in t

i : space counter
 j : time counter

Substitute in PDE and let $\lambda = k \Delta t / (\Delta x)^2$

$$T_{i,j+1} = T_{i,j} + \lambda (T_{i+1,j} - 2T_{i,j} + T_{i-1,j})$$

$i, j = 0, 1, 2, \dots, n$

Heat difference equation

To solve heat equation, we need 2 boundary conditions and one initial condition.

BC's

$$T(0, t) = T_1$$

$$T(L, t) = T_2$$

IC's

$$T(x, 0) = f(x)$$

Example: For a bar with 10cm length, the heat equation is: ②

$$\frac{\partial T}{\partial t} = K \frac{\partial^2 T}{\partial x^2}$$

$$\begin{array}{l} \text{BC's} \\ T(0,t) = 100^\circ\text{C} \\ T(10,t) = 50^\circ\text{C} \end{array}$$

$$\begin{array}{l} \text{IC's} \\ T(x,0) = 0 \end{array}$$

Use Explicit method to solve this PDE. Given $\Delta x = 2\text{ cm}$
 $\Delta t = 0.1$ and $K = 0.49$. Total time $t = 0 \rightarrow 0.2$ seconds

Solution

i	x_i
0	$x_0 = 0$
1	$x_1 = 2$
2	$x_2 = 4$
3	$x_3 = 6$
4	$x_4 = 8$
5	$x_5 = 10$

j	t_j
0	$t_0 = 0$
1	$t_1 = 0.1$
2	$t_2 = 0.2$

① we know ① at $x_0 = 0$, $T = 100^\circ\text{C}$ for all t

② at $x_5 = 10$, $T = 50^\circ\text{C}$ for all t

③ x_1 is always zero for $t_0 = 0$

$\Rightarrow$ we need

x_1, t_1

x_2, t_1

x_3, t_1

x_4, t_1

x_1, t_2

x_2, t_2

x_3, t_2

x_4, t_2

Now, use

$$T_{i,j+1} = T_{i,j} + \lambda (T_{i+1,j} - 2T_{i,j} + T_{i-1,j}) \quad , \quad \lambda = \frac{k \Delta t}{(\Delta x)^2} = 0.02$$

For x_1, t_1 ($i=1, j=0$)

$$T_{1,1} = T_{1,0} + \lambda (T_{2,0} - 2T_{1,0} + T_{0,0})$$

$$T_{1,0} = 0, \quad T_{2,0} = 0, \quad T_{0,0} = 100$$

$$\Rightarrow T_{1,1} = 0 + 0.02(0 - (2)(0) - 100) \Rightarrow \boxed{T_{1,1} = 2^\circ \text{C}}$$

For point x_2, t_1 ($i=2, j=0$)

$$T_{2,1} = T_{2,0} + \lambda (T_{3,0} - 2T_{2,0} + T_{1,0})$$

$$T_{2,0} = 0, \quad T_{3,0} = 0, \quad T_{1,0} = 0$$

$$\Rightarrow \boxed{T_{2,1} = 0}$$

For point x_3, t_1 ($i=3, j=0$)

$$T_{3,1} = T_{3,0} + \lambda (T_{4,0} - 2T_{3,0} + T_{2,0})$$

$$T_{3,0} = 0, \quad T_{4,0} = 0, \quad T_{2,0} = 0$$

$$\Rightarrow T_{3,1} = 0$$

Keep going to compute T at all other points

See example 30.1

Boundary conditions

- 1- Fixed type (Dirichlet) $\rightarrow$ we discussed this in Previous example
- 2- Derivative type (Neumann)

Derivative type or Neumann BC's

For the previous example, If $\frac{dT}{dx}(0,t) = f(t)$

- To Find temperature at $x_0=0$ and t_j ($i=0, j=j$)

$$T_{0,j+1} = T_{0,j} + \lambda (T_{1,j} - 2T_{0,j} + \underline{T_{-1,j}})$$

For the derivative BC

$$\frac{dT}{dx} = \frac{T_{1,j} - T_{-1,j}}{2\Delta x} \Rightarrow T_{-1,j} = T_{1,j} - 2\Delta x \frac{dT}{dx}$$

$\Rightarrow$ At $x_0=0$, any t

$$T_{0,j+1} = T_{0,j} + \lambda \left(T_{1,j} - 2T_{0,j} + T_{1,j} - 2\Delta x \frac{dT}{dx} \right)$$

$$T_{0,j+1} = T_{0,j} + 2\lambda (T_{1,j} - T_{0,j} - \Delta x f(t_j))$$

Solve problem 30.2 For more details

Chapter 29, Heat - Equation, cont'd

30.3 A Simple Implicit method

In this method, we find the find differences at t_{j+1} , thus:

$$\frac{\partial^2 T}{\partial x^2} = \frac{T_{i+1,j+1} - 2T_{i,j+1} + T_{i-1,j+1}}{(\Delta x)^2}$$

$$\frac{\partial T}{\partial t} = \frac{T_{i,j+1} - T_{i,j}}{\Delta t}$$

substitute in PDE $\frac{\partial T}{\partial t} = K \frac{\partial^2 T}{\partial x^2}$

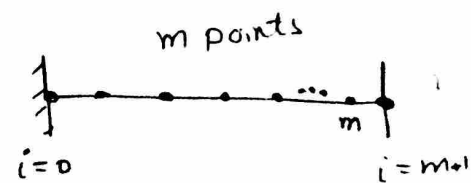
$$\Rightarrow -\lambda T_{i-1,j+1} + (1+2\lambda)T_{i,j+1} - \lambda T_{i+1,j+1} = T_{i,j}$$

where $\lambda = \frac{K \Delta t}{(\Delta x)^2}$

This equation applies to all points but not boundary points (start and end points) $\Rightarrow$ Modification required!

For left point ($i=0$)

$$T_{0,j+1} = f_0(t_{j+1}) \quad \text{the } \underline{BC}$$



For point $i=1$ and any t

$$(1+2\lambda)T_{1,j+1} - \lambda T_{2,j+1} = T_{1,j} + \lambda f_0(t_{j+1})$$

For point ($i=m$), before the last end.

$$-\lambda T_{m-1,j+1} + (1+2\lambda)T_{m,j+1} = T_{m,j} + \lambda f_{m+1}(t_{j+1})$$

the BC

$$f_{m+1}(t_{j+1}) = T_{m+1,j+1}$$

Example For the previous example, use the Implicit method!

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$$\frac{\partial T}{\partial t} = k \frac{\partial^2 T}{\partial x^2}$$

$$L = 10 \text{ cm}$$

BC's

$$T(0, t) = 100^\circ \text{C}$$

$$T(10, t) = 50^\circ \text{C}$$

IC's

$$T(x, 0) = 0$$

$$\Delta x = 2 \text{ cm}, \Delta t = 0.1, \text{ total time } 0.2 \text{ seconds}, k = 0.49$$

Solution $\lambda = \frac{k \Delta t}{(\Delta x)^2} = 0.02$

i	x_i
0	$x_0 = 0$
1	$x_1 = 2$
2	$x_2 = 4$
3	$x_3 = 6$
4	$x_4 = 8$
5	$x_5 = 10$

j	t_j
0	$t_0 = 0$
1	$t_1 = 0.1$
2	$t_2 = 0.2$

we need to find $x_1 \rightarrow x_4$ for t_1 and t_2

① at t_1 (take $j=0$)

point x_1 ($i=1$)

$$(1 + 2\lambda) T_{1,j+1} - \lambda T_{2,j+1} = T_{1,j} + \lambda f_0(t_{j+1})$$

$$(1 + 2(0.02)) T_{1,1} - 0.02 T_{2,1} = T_{1,0} + \lambda (100)$$

$$\Rightarrow (1.04 T_{1,1} - 0.02 T_{2,1} = 2.0) \quad - \text{Eq (1)}$$

For point $x_2 \Rightarrow (i=2)$

$$-0.02 T_{1,1} + (1 + 2(0.02)) T_{2,1} - 0.02 T_{3,1} = T_{2,0} = 0$$

$$\Rightarrow (-0.02 T_{1,1} + 1.04 T_{2,1} - 0.02 T_{3,1} = 0) \quad - \text{Eq (2)}$$

For point $x_3 \Rightarrow i=3$

$$-0.02 T_{2,1} + (1 + (2)(0.02)) T_{3,1} - 0.02 T_{4,1} = \overline{T_{3,0}} = 0$$

$$\Rightarrow \{-0.02 T_{2,1} + 1.04 T_{3,1} - 0.02 T_{4,1} = 0\} \quad \text{--- Eq (3)}$$

For point x_4 ($i=4=m$)

$$-0.02 T_{3,1} + (1 + (2)(0.02)) T_{4,1} = \overline{T_{4,0}} + 0.02 \frac{p}{5} (t_{j+1})$$

BC
= 50°C

$$\{-0.02 T_{3,1} + 1.04 T_{4,1} = 1\} \quad \text{--- Eq (4)}$$

Matrix Form

$$\begin{bmatrix} 1.04 & -0.02 & 0 & 0 \\ -0.02 & 1.04 & -0.02 & 0 \\ 0 & -0.02 & 1.04 & -0.02 \\ 0 & 0 & -0.02 & 1.04 \end{bmatrix} \begin{Bmatrix} T_{1,1} \\ T_{2,1} \\ T_{3,1} \\ T_{4,1} \end{Bmatrix} = \begin{Bmatrix} 2 \\ 0 \\ 0 \\ 1 \end{Bmatrix}$$

Solve $\Rightarrow T_{1,1} = 2.00$, $T_{2,1} = 0.041$, $T_{3,1} = 0.021$, $T_{4,1} = 1.00$

For $t_2 = 0.02$ Use $j=1$ and repeat all point $x_i \rightarrow x_{j+1}$ to get another system of 4-linear equations

* The coefficient matrix, remains the same. However, $\{T_{i,2}\}$ and resultant vectors should change

Solve $\Rightarrow T_{1,2} = 3.93$

$T_{2,2} = 0.12$

$T_{3,2} = 0.07$

$T_{4,2} = 1.96$

Chapter 30, Parabolic eq.

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30.4 Crank - Nicolson method (CN-method)

* CN method is another Implicit method used to solve heat equation

$$\frac{\partial T}{\partial t} = k \frac{\partial^2 T}{\partial x^2}$$

α However, it combines both Explicit and implicit solvers.

$$\frac{\partial T}{\partial t} = \frac{T_{i,j+1} - T_{i,j}}{\Delta t}$$

and

$$\frac{\partial^2 T}{\partial x^2} = \frac{1}{2} \left[\overset{\text{Explicit}}{\frac{T_{i+1,j} - 2T_{i,j} + T_{i-1,j}}{(\Delta x)^2}} + \overset{\text{Implicit}}{\frac{T_{i+1,j+1} - 2T_{i,j+1} + T_{i-1,j+1}}{(\Delta x)^2}} \right]$$

↪
Averages both explicit and Implicit methods!

Substitute in the PDE and collect terms: Eq 1-C

$$-\lambda T_{i-1,j+1} + 2(1+\lambda)T_{i,j+1} - \lambda T_{i+1,j+1} = \lambda T_{i-1,j} + 2(1-\lambda)T_{i,j} + \lambda T_{i+1,j}$$

where $\lambda = \frac{k \Delta t}{(\Delta x)^2}$

As we did for the implicit method, at the boundary condition point ($i=0$)

$T_{0,j+1} = f_0(t_{j+1})$ and at the ($i=m$), point $T_{m+1,j+1} = f_{m+1}(t_{j+1})$

Thus, for point ($i=1$) at any t . → BC

$$2(1+\lambda)T_{1,j+1} - \lambda T_{2,j+1} = \lambda f_0(t_j) + 2(1-\lambda)T_{1,j} + \lambda f_0(t_{j+1})$$
Eq 2-C

For point ($i=m$), before the last end point

$$-\lambda T_{m-1,j+1} + 2(1+\lambda)T_{m,j+1} = \lambda f_{m+1}(t_j) + 2(1-\lambda)T_{m,j} + \lambda T_{m-1,j} + \lambda f_{m+1}(t_{j+1})$$
Eq 3-C

Example 8- For the previous example, use CN method to solve (9)

$$\frac{\partial T}{\partial t} = k \frac{\partial^2 T}{\partial x^2}, \quad L = 10 \text{ cm}, \quad \begin{array}{l} \text{BC's} \\ T(0, t) = 100^\circ \text{C} \\ T(10, t) = 50^\circ \text{C} \end{array} \quad \begin{array}{l} \text{IC's} \\ T(x, 0) = 0 \end{array}$$

$$\Delta x = 2 \text{ cm}, \quad \Delta t = 0.1 \text{ sec}, \quad \text{total time } 0.2 \text{ seconds}, \quad k = 0.49$$

Solution $\lambda = \frac{k \Delta t}{(\Delta x)^2} = 0.02$

$$\begin{array}{c|c} i & x_i \\ \hline 0 & x_0 = 0 \\ 1 & x_1 = 2 \\ 2 & x_2 = 4 \\ 3 & x_3 = 6 \\ 4 & x_4 = 8 \\ 5 & x_5 = 10 \end{array}$$

$$\begin{array}{c|c} j & t_j \\ \hline 0 & t_0 = 0 \\ 1 & t_1 = 0.1 \\ 2 & t_2 = 0.2 \end{array}$$

* we need to find x_i for $i=1 \rightarrow 4$ at t_1 and t_2

① At t_1 ($j=0$) (Eq 2-C)
point x_1 ($i=1$)

$$2(1+0.02)T_{1,1} - (0.02)T_{2,1} = (0.02)f_0(t_0) - (2)(1-0.02)T_{1,0} + (0.02)f_0(t_1)$$

$\overset{100^\circ \text{C}}{f_0(t_0)} \quad \overset{\text{IC}}{f_0(t_1)} = 100^\circ \text{C (BC)}$

$$2.04 T_{1,1} - 0.02 T_{2,1} = 4.0 \quad \text{--- (1)}$$

point x_2 ($i=2$), Eq 1-C

$$-0.02 T_{1,1} + 2(1+0.02)T_{2,1} - 0.02 T_{3,1} = 0.02 T_{1,0} + 2(1-0.02)T_{2,0} + 0.02 T_{3,0}$$

$\overset{0}{T_{1,0}} \quad \overset{\text{IC}}{T_{2,0}} \quad \overset{\text{IC}}{T_{3,0}} = 0$

$$-0.02 T_{1,1} + 2.04 T_{2,1} - 0.02 T_{3,1} = 0 \quad \text{--- (2)}$$

point x_3 ($i=3$), Eq 1-C

$$-0.02 T_{2,1} + 2.04 T_{3,1} - 0.02 T_{4,1} = 0 \quad \text{--- 3}$$

point x_4 ($i=4$), Eq 3-C

$$-0.02 T_{3,1} + 2.04 T_{4,1} = 2.07 \quad \text{--- 4}$$

⇒ Collect in Matrix Form

(10)

$$\begin{bmatrix} 2.04 & -0.02 & 0 & 0 \\ -0.02 & 2.04 & -0.02 & 0 \\ 0 & -0.02 & 2.04 & -0.02 \\ 0 & 0 & -0.02 & 2.04 \end{bmatrix} \begin{Bmatrix} T_{1,1} \\ T_{2,1} \\ T_{3,1} \\ T_{4,1} \end{Bmatrix} = \begin{Bmatrix} 4.0 \\ 0 \\ 0 \\ 2.08 \end{Bmatrix}$$

Solve $T_{1,1} = 2.045$, $T_{2,1} = 0.021$, $T_{3,1} = 0.011$, $T_{4,1} = 1.023$

* For $t_2 = 0.02$ use $j=1$ and repeat for all points $x_1 \rightarrow x_4$ to get another system of 4-linear equations

* The coefficient matrix, remains the same. However, $\{T_{i,2}\}$ and resultant vectors should change

Solve ⇒ $T_{1,2} = 4.007$

$$T_{2,2} = 0.083$$

$$T_{3,2} = 0.042$$

$$T_{4,2} = 2.004$$

Chapter 30, Heat Equation

(11)

30.5 Heat Equation in two spatial dimensions

$$\frac{\partial T}{\partial t} = K \left(\frac{\partial^2 T}{\partial x^2} + \frac{\partial^2 T}{\partial y^2} \right),$$

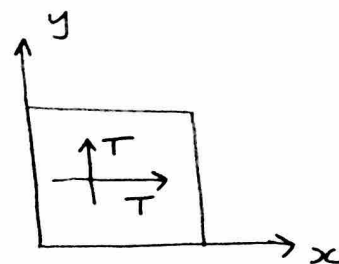
$$T(x, y, t)$$

T: temp

x, y: space

K: constant

t: time



we use alternating-direction implicit

(ADI) method. we solve the PDE for each time increment (Δt) in

two steps:

1st step

$$\frac{\partial T}{\partial t} = \frac{T_{i,j}^{K+1/2} - T_{i,j}^K}{\Delta t/2}$$

i: x-direction counter

j: y-direction counter

K: time counter

$$\frac{\partial^2 T}{\partial x^2} = \frac{T_{i+1,j}^K - 2T_{i,j}^K + T_{i-1,j}^K}{(\Delta x)^2}$$

Δx : step size in x

Δy : step size in y

Δt : step size in t

$$\frac{\partial^2 T}{\partial y^2} = \frac{T_{i,j+1}^{K+1/2} - 2T_{i,j}^{K+1/2} + T_{i,j-1}^{K+1/2}}{(\Delta y)^2}$$

Substitute in PDE, for $\Delta x = \Delta y$, $\lambda = \frac{K \Delta t}{(\Delta x)^2}$ or $\lambda = \frac{K \Delta t}{(\Delta y)^2}$

$$-\lambda T_{i,j-1}^{K+1/2} + 2(1+\lambda)T_{i,j}^{K+1/2} - \lambda T_{i,j+1}^{K+1/2} = \lambda T_{i-1,j}^K + 2(1-\lambda)T_{i,j}^K + \lambda T_{i+1,j}^K \quad \text{Eq(a)}$$

2nd step:

$$\frac{\partial T}{\partial t} = \frac{T_{i,j}^{K+1} - T_{i,j}^{K+1/2}}{\Delta t/2}, \quad \frac{\partial^2 T}{\partial x^2} = \frac{T_{i+1,j}^{K+1} - 2T_{i,j}^{K+1} + T_{i-1,j}^{K+1}}{(\Delta x)^2}, \quad \frac{\partial^2 T}{\partial y^2} = \text{as 1st step}$$

Substitute in PDE, $\Delta x = \Delta y$, $\lambda = \frac{K \Delta t}{(\Delta x)^2}$ or $\lambda = \frac{K \Delta t}{(\Delta y)^2}$

Eq(b)

$$-\lambda T_{i-1,j}^{K+1} + 2(1+\lambda)T_{i,j}^{K+1} - \lambda T_{i+1,j}^{K+1} = \lambda T_{i,j-1}^{K+1/2} + 2(1-\lambda)T_{i,j}^{K+1/2} + \lambda T_{i,j+1}^{K+1/2}$$

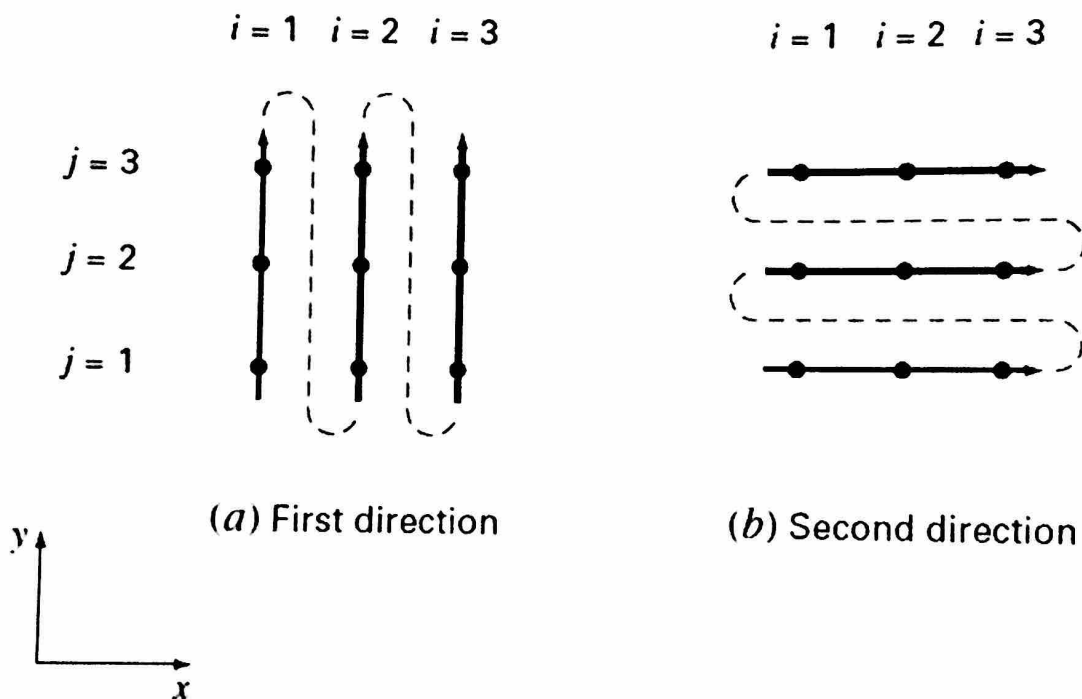
In Eq(a), $\frac{\partial^2 T}{\partial x^2}$ are known. However, $\frac{\partial^2 T}{\partial y^2}$ are not

(12)

$\Rightarrow$ Obtain all $T^{k+1/2}$ terms $\Rightarrow$ Use them in Eq(b)

In Eq(b), $\frac{\partial^2 T}{\partial x^2}$ are now unknown. However, $\frac{\partial^2 T}{\partial y^2}$ are known from Eq(a)

$\Rightarrow$ obtain all T^{k+1} terms.



we first solve for y -direction, then for x -direction at each time step

Example Use ADI, to solve

$$\frac{\partial T}{\partial t} = k \left(\frac{\partial^2 T}{\partial x^2} + \frac{\partial^2 T}{\partial y^2} \right)$$

BC's

$$T(0, y, t) = 75^\circ\text{C}$$

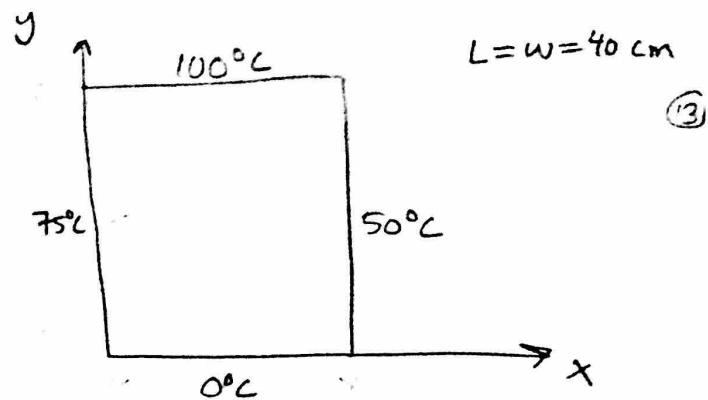
$$T(4, y, t) = 50^\circ\text{C}$$

$$T(x, 0, t) = 0^\circ\text{C}$$

$$T(x, 4, t) = 100^\circ\text{C}$$

IC's

$$T(x, y, 0) = 0$$



Use, $\Delta x = 10\text{ cm}$, $\Delta y = 10\text{ cm}$, $\Delta t = 10\text{ s}$, total time = 10 seconds, $Er = 0.835$

Solution $\lambda = \frac{k \Delta t}{(\Delta x)^2} = \frac{(0.835)(10)}{(10)^2} = 0.0835$

We need to find $T_{i,j}$ ($i=1,2,3$ and $j=1,2,3$)

For step 1 ($t = 5\text{ seconds}$, $\Delta t/2$), Eq(a)

- point (1,1) $\circ$ $k \Delta t = 0.835$

$$\Rightarrow 2.167 T_{1,1} - 0.0835 T_{1,2} = 6.2625$$

- point (1,2)

$$-0.0835 T_{1,1} + 2.167 T_{1,2} - 0.0835 T_{1,3} = 6.2625$$

- point (1,3)

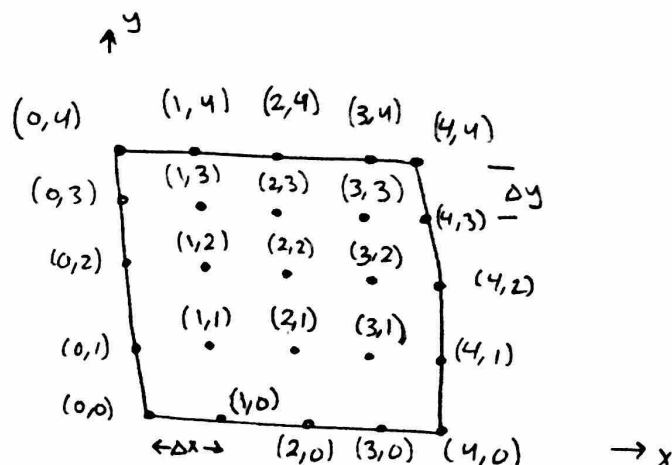
$$-0.0835 T_{1,2} + 2.167 T_{1,3} = 14.6125$$

Matrix Form

$$\begin{bmatrix} 2.167 & -0.0835 & 0 \\ -0.0835 & 2.167 & -0.0835 \\ 0 & -0.0835 & 2.167 \end{bmatrix} \begin{Bmatrix} T_{1,1} \\ T_{1,2} \\ T_{1,3} \end{Bmatrix} = \begin{Bmatrix} 6.2625 \\ 6.2625 \\ 14.6125 \end{Bmatrix}$$

Solve

$$T_{1,1} = 3.02, \quad T_{1,2} = 3.27, \quad T_{1,3} = 6.87$$



In a similar fashion, we find $T_{2,1}, T_{2,2}, T_{2,3}$ and $T_{3,1}, T_{3,2}, T_{3,3}$

$$T_{2,1} = 0.13, T_{2,2} = 3.27, T_{2,3} = 4.13$$

$$T_{3,1} = 2.02, T_{3,2} = 2.25, T_{3,3} = 6.03$$

Now, we do step 2 ($t = 10 \text{ sec}, k+1$), Eq(6)

- points (1,1), (2,1) and (3,1), matrix Form

$$\begin{bmatrix} 2.167 & -0.0835 & 0 \\ 0.0835 & 2.167 & -0.0835 \\ 0 & -0.0835 & 2.167 \end{bmatrix} \begin{Bmatrix} T_{1,1} \\ T_{2,1} \\ T_{3,1} \end{Bmatrix} = \begin{Bmatrix} 12.064 \\ 0.2577 \\ 8.062 \end{Bmatrix}$$

In a similar fashion, we find $T_{1,2}, T_{2,2}, T_{3,2}$ and $T_{1,3}, T_{2,3}, T_{3,3}$

$$T_{1,2} = 6.168, T_{2,2} = 0.824, T_{3,2} = 4.236$$

$$T_{1,3} = 13.112, T_{2,3} = 8.321, T_{3,3} = 11.361$$

this method can be repeated for any period of time.

End of Chapter 30!