

Linear Momentum and Collisions



Prof. Rashad Badran



Linear Momentum and Collisions

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Momentum and Impulse



Linear Momentum

Definition of momentum:

- Momentum is a *vector* quantity: it has magnitude (*mv*) and direction (the same as velocity vector)
 - Momentum of a car driving North at 20 *m/s* is different from momentum of the same car driving East at the same speed
 - Ball thrown by a major-league pitcher has greater magnitude of momentum than the same ball thrown by a child because the speed is greater
- □ Units of momentum (SI): mass × speed, kg·m/s

Linear Momentum and Kinetic Energy

The kinetic energy and magnitude of momentum of an object are:

$$K = \frac{1}{2}mv^{2} - - - - (1)$$

$$p = mv - - - - (2)$$

Multiply and divide the RHS of equation (1) by *m* to get

$$K = \frac{1}{2m}m^2v^2 - - - -(3)$$

Square both sides of equation (2) to get

Substitute equation (4) into (3) to get

$$K = \frac{p^2}{2m} - - - -(5) \qquad or \Longrightarrow p = \sqrt{2mK}$$

Linear Momentum

Problem

Given the mass and speed of objects A and B as shown in table and figure, find the magnitude of the momentum and the kinetic energy for each object. 6.0 m/s

MassSpeed2.0 kgObject A2.0 kg6.0 m/sObject B6.0 kg2.0 m/sSolution $p_A = m_A v_A = (2.0kg)(6.0m/s) = 12kg \cdot m/s$

$$K_{A} = \frac{1}{2}m_{A}v_{A}^{2} = \frac{1}{2}(2.0kg)(6.0m/s)^{2} = 36J$$

$$p_B = m_B v_B = (6.0 kg)(2.0 m/s) = 12 kg \cdot m/s$$

$$K_B = \frac{1}{2}m_B v_B^2 = \frac{1}{2}(6.0kg)(2.0m/s)^2 = 12J$$

Linear Momentum

Problem

An object has a kinetic energy of 275 J and a momentum of magnitude 25 kg.m/s. Find the speed and mass of the object.



Use the equation that relates kinetic energy to momentum, namely:

$$K = \frac{p^2}{2m}$$

Substitute K = 275J and p = 25 kg. m/s to get

$$275J = \frac{\left(25kg.m/s\right)^2}{2m} \implies m = 1.136kg$$

Substitute *m* into momentum equation p = mv

$$25kg.m/s = (1.136kg)v \qquad \implies v = 22m/s$$

Momentum From Newton's 2nd Law

■ We will once again re-express *Newton's 2nd law* in terms of momentum.

$$\sum \vec{F} = m\vec{a} \qquad \because \vec{a} = \frac{d\vec{v}}{dt} \qquad \Rightarrow \sum \vec{F} = m\frac{d\vec{v}}{dt} = \frac{d}{dt}(m\vec{v}) \qquad \therefore \sum \vec{F} = \frac{d\vec{p}}{dt}$$

- The *linear momentum* of a particle of mass *m* moving with velocity \vec{v} is a vector quantity defined as the product of particle's mass and velocity: $\vec{p} = m\vec{v}$
- Newton's 2nd law is re-defined as the rate of change of momentum.
- Components of momentum:

$$\vec{p}: p_x = mv_x \quad p_y = mv_y \quad p_z = mv_z$$

Internal Forces: (An Isolated System)

- **Internal forces**: the forces that the particles of the system exert on each other (for any system)
- Forces exerted on any part of the system by some object outside it called external forces
- For the system of two astronauts, the internal forces are <u>*F*</u>_{BonA}, exerted by particle B on particle A, and <u>*F*</u>_{AonB}, exerted by particle A on particle B
- There are NO external forces: we have isolated system

$$\vec{F}_{BonA} = \frac{d\vec{p}_A}{dt} \quad \vec{F}_{AonB} = \frac{d\vec{p}_B}{dt} \quad \vec{F}_{AonB} = -\vec{F}_{BonA}$$
$$\vec{F}_{AonB} + \vec{F}_{BonA} = \frac{d\vec{p}_A}{dt} + \frac{d\vec{p}_B}{dt} = \frac{d(\vec{p}_A + \vec{p}_B)}{dt} = 0$$



- **Total momentum** of two particles is the vector sum of the momenta of individual particles
- If system consist of any number of particles A, B, ... $\vec{p}_{Tot} = \vec{p}_A + \vec{p}_B + ... = m_A \vec{v}_A + m_B \vec{v}_B + ...$

- Concept of *momentum* is particularly important in situations when you have *two* or *more* interacting *bodies*
- Consider idealized system of two particles: two astronauts floating in the zero-gravity environment
 - Astronauts touch each other (each particle exerts force on another)
 - Newton's 3rd law: these forces are equal and opposite
 - Hence, *impulses* that act on two particles are equal and opposite



• The time rate of change of the total momentum is zero. Hence the total momentum of the system is constant, even though the individual momenta of the particles that make up the system can change.

$$\vec{F}_{AonB} + \vec{F}_{BonA} = \frac{d\vec{p}}{dt} = 0$$

- If there are external forces acting on the system, they must be included into equation above along with internal forces.
- Then the total momentum is not constant in general. But if vector sum of external forces is zero, these forces do not contribute to the sum, and $\frac{d\vec{p}}{dt} = 0$.



Principle of conservation of momentum:

- If the vector sum of the external forces on a system is zero, the total momentum of the system is constant
 - This principle does not depend on the detailed nature of internal forces that act between members of the system: we can apply it even if we know very little about the internal forces.
 - The principle acts only in internal frame of reference (because we used Newton's 2nd law to derive it!)



Conceptual problem:

Is the total momentum conserved for the following cases:

Two balls collide on the billiard table that is free of friction.

- (a) Is the total momentum of the two ball system the same before and after the collision?
- (b) Answer (a) for a system that contains only one ball.

Answer:

(a) The total momentum is conserved



(a)

(b) The total momentum of one ball is NOT conserved



Problem-Solving Strategy

IDENTIFY *the relevant concepts:*

- Before applying conservation of momentum to a problem, you must first decide whether momentum is conserved!
- This will be true *only* if the vector sum of the external forces acting on the system of particles is zero.
- If this is not the case, you can't use conservation of momentum.

Problem-Solving Strategy

SET UP the problem using the following steps:

- 1. Define a *coordinate system*. Make a *sketch* showing the coordinate axes, including the positive direction for each. Make sure you are using an inertial frame of reference. Most of the problems in this course deal with two-dimensional situations, in which the vectors have only *x* and *y*-components; all of the following statements can be generalized to include *z*-components when necessary.
 - 2. Treat each body as a particle. Draw "before" and "after" sketches, and include vectors on each to represent all known velocities. Label the vectors with magnitudes, angles, components, or whatever information is given, and give each unknown magnitude, angle, or component an algebraic symbol. You may use the unprimed and primed letters for velocities before and after interaction, respectively.
 - 3. As always, identify the *target* variable(s) from among the unknowns.

Problem-Solving Strategy

EXECUTE the solution as follows:

- 1. Write equation in terms of symbols equating the total *initial x*-component of momentum (*before* the interaction) to the total *final x*-component of momentum (*after*), using $p_x = mv_x$ for each particle.
- 2. Write another equation for *y*-components, using $p_y = mv_y$ for each particle.
 - Remember that the x- and y-components of velocity or momentum are never added together in the same equation!
 - Even when all the velocities lie along a line (such as the x-axis), components of velocity along this line can be positive or negative; be careful with signs!
 - 3. Solve these equations to determine whatever results are required. In some problems you will have to convert from the x- and y-components of a velocity to its magnitude and direction, or the reverse.

4. In some problems, energy considerations give additional relationships among the various velocities.

Problem-Solving Strategy

EVALUATE your answer:

- Does your answer make physical *sense*?
- If your target variable is a certain body's momentum, check that the *direction* of the momentum is *reasonable*.

Conservation of Total Momentum in Explosions



Note: v_b and v_g are in opposite directions

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 $v_a = -3.75 m/s$

Problem

Two blocks of masses m and 3m are placed on a frictionless, horizontal surface. A light spring is attached to the more massive block, and the blocks are pushed together with the spring between them. A cord initially holding the blocks together is burned: after that happens, the block of mass 3m moves to the right with a speed of 2 m/s. (a) What is the velocity of the block of mass m? (b) Find the system original elastic potential energy taking m = 0.35 kg. (c) Is the original energy in the spring or in the cord? (d) Explain your answer in part (c)





After

Before

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Conservation of Total Momentum

Solution

(a) What is the velocity of the block of mass m?

$$(\vec{p}_1 + \vec{p}_2)_{Before} = (\vec{p}_1 + \vec{p}_2)_{After}$$
$$(m_1 \vec{v}_1 + m_2 \vec{v}_2)_{Before} = (m_1 \vec{v}_1 + m_2 \vec{v}_2)_{After}$$

Conservation of linear momentum in 1-D:

$$(m_1v_1 + m_2v_2)_{Before} = (m_1v_1 + m_2v_2)_{After}$$

$$m_{1} = m, \qquad m_{2} = 3m, \qquad v_{1b} = v_{2b} = 0, \qquad After$$

$$v_{2a} = 2 m/s, \qquad v_{1a} = ?$$

$$(0+0)_{Before} = (mv_{1a} + 3m(2m/s))_{After} \qquad \Rightarrow v_{1a} = -6m/s$$



m

Solution

(b) Find the system original elastic potential energy taking m = 0.35 kg.

$$K_{Tot} = \frac{1}{2} (m_1 v_1^2 + m_2 v_2^2)$$

$$m_1 = m, \qquad m_2 = 3m, \qquad v_{2a} = 2 m/s \qquad v_{1a} = -6m/s$$

$$K_{Tot} = \frac{1}{2} (m v_{1a}^2 + 3m v_{2a}^2)$$

$$= \frac{1}{2} (0.35kg) [(6m/s)^2 + (3)(2m/s)^2] = 8.4J$$

$$U_{Elastic} = K_{Tot} = 8.4J$$

(c) Is the original energy in the spring or in the cord? It is the potential energy stored in the spring

(d) Explain your answer in part (c). This is because the spring was compressed before the release of two masses

A 60-kg archer stands at rest on frictionless ice and fires a **Problem** 0.5 kg arrow horizontally at 50m/s with what velocity does the archer move across the ice after firing arrow?







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 $v'_{arrow} = 50 m/s$



A 60-kg archer stands at rest on frictionless ice and fires a 0.5 kg arrow horizontally at 50m/s with what velocity does the archer move across the ice after firing arrow?

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Solution $(m_1\vec{v}_1 + m_2\vec{v}_2) = (m_1\vec{v}_1' + m_2\vec{v}_2')$ $v_1 = v_2 = 0$ $v'_2 = v'_{arrow} = 50m/s$ $v'_1 = v'_{archer} = ?$ $m_1 = 60 \ kg$ $m_2 = 0.5 \ kg$ $0 = (60kg)\vec{v}_1' + (0.5kg)(50\hat{i}m/s)$ $\vec{v}_1' = -0.42\hat{i}m/s$ $v'_2 = v'_{arrow} = 50 m/s$ $v'_{l} = v'_{archer} = ?$



In our discussion of work and energy we re-expressed *Newton*'s *Second Law* in an integral form called Work-Energy Theorem (*W*_{Net} = △*K*) which states that the total work done on a particle equals the change in the kinetic energy of the particle.

$$dW_{Net} = F_x dx$$

From Newton's 2nd law $F_x = ma_x$ or $F_x = m\frac{dv_x}{dt}$ Thus $dW_{Net} = m\frac{dv_x}{dt}dx$ The variable x can be changed to v_x where $v_x = \frac{dx}{dt}$ $dW_{Net} = mv_x dv_x$ Integrate both sides $\Rightarrow \int dW_{Net} = m\int_{v_{xi}}^{v_{xf}} v_x dv_x$ $\therefore W_{Net} = \frac{1}{2}m(v_{xf}^2 - v_{xi}^2) \Rightarrow W_{Net} = K_f - K_i = \Delta K$

Nonisolated System:(Momentum and Impulse)

□ *Newton's 2nd law* in terms of momentum shows that

- Rapid change in momentum requires a large net force
- Gradual change in momentum requires less net force
- □ This principle is used in the design of safety air bags in cars
 - The driver of fast-moving car has a large momentum (the product of the driver's mass and velocity).
 - If car stops suddenly in a collision, driver's momentum becomes zero due to collision with car parts (steering wheel and windshield)
 - Air bag causes the driver to lose momentum more gradually than would abrupt collision with the steering wheel, reducing the force exerted on the driver (and the possibility for injury)
- Same principle applies to the padding used to package fragile objects for shipping
 The Prof. Rasha

Nonisolated System:(Momentum and Impulse)

□ Consider a particle acted on by a *constant* net force $\sum \vec{F}$ during a time interval Δt from t_i to t_f . The *impulse* of the net force \vec{J} is defined to be the product of the net force and the time interval:

$$\vec{J} = \sum \vec{F}(t_f - t_i) = \sum \vec{F} \Delta t$$

For constant net force

- Impulse is a vector quantity.
 - Its direction is the same as the net force
 - Its magnitude is the product of the magnitude of the net force and the length of <u>time</u> the net force acts
- **Units** of impulse (SI): *force* \times *time*, *N*·*s*
 - $1 N = 1 kg \cdot m/s^2 \rightarrow N \cdot s = kg \cdot m/s$ (**same** as momentum)

□ If the net force is constant, then $\frac{d\bar{p}}{dt}$ is also constant and equals to the total change in momentum during the time interval $t_2 - t_1$, divided by this time interval:

$$\sum \vec{F} = const = \frac{d\vec{p}}{dt} = \frac{\vec{p}_f - \vec{p}_i}{t_f - t_i} \qquad \sum \vec{F}(t_f - t_i) = \vec{p}_f - \vec{p}_i$$

 $\vec{J} = \vec{p}_f - \vec{p}_i = \Delta \vec{p}$ (Impulse – Momentum Theorem)

Impulse – Momentum Theorem: The change in momentum of a particle during a time interval equals the impulse of the net force that acts on the particle during that interval.

- ❑ We will once again re-express *Newton's 2nd law* in an integral form. However, in this case the *independent variable* will be *time* rather than **position** as was the case for the Work-Energy Theorem.
 - Impulse Momentum Theorem also holds when forces are NOT constant. To see this, lets integrate both sides of Newton's 2nd law

$$\int_{t_1}^{t_2} \sum_{t_1} \vec{F} dt = \int_{t_1}^{t_2} \frac{d\vec{p}}{dt} dt = \int_{t_1}^{t_2} d\vec{p} = \vec{p}_2 - \vec{p}_1$$



$$\vec{J} = \int_{t_1}^{t_2} \sum \vec{F} dt$$

(General definition of impulse)

• We can define an *average* net force $\sum \vec{F}$ such that even when $\sum \vec{F}$ is **NOT** constant, the impulse \vec{J} is given by

$$\vec{J} = \vec{F}_{av}(t_2 - t_1)$$

• The impulse can be interpreted as the "area" under the graph of F(t) versus t. The xcomponent of impulse of the net force ΣF_x between t_1 and t_2 equals the area under ΣF_x -t curve, which also equals the area under rectangle with height $(F_{av})_x$



$$J_{x} = \int_{t_{1}}^{t_{2}} \sum F_{x} dt = (F_{av})_{x} (t_{2} - t_{1}) = p_{2x} - p_{1x} = mv_{2x} - mv_{1x}$$
$$J_{y} = \int_{t_{1}}^{t_{2}} \sum F_{y} dt = (F_{av})_{y} (t_{2} - t_{1}) = p_{2y} - p_{1y} = mv_{2y} - mv_{1y}$$
$$\mathcal{J}_{y} \text{ Prof. Rashad Badran}$$

Problem

Solution

ta

The magnitude of the net force exerted in the x direction on a 2.5-kg particle varies in time as shown in the figure. Find (a) the impulse of the force over the 5-s time interval, (b) the final velocity the particle attains if it is originally at rest, (c) its final velocity if its original velocity is $-2\hat{i}m/s$, and (d) the average force exerted on the particle for the time interval between 0 and 5 s.

(a)
$$J = \int_{t_1}^{t_2} \sum F dt = (F_{av})(t_2 - t_1)$$

J = Area under the curve from t_1 to t_2

J = 0.5((5+1)s)(4N) = 12 N. s due east

(b)
$$J_x = p_{2x} - p_{1x} = mv_{2x} - mv_{1x}$$

 $12N.s = (2.5kg)(v_{2x} - 0)$
 $v_{2x} = 4.8m/s$ due east



Problem

Solution

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Exercise

- A baseball (m = 0.14kg) has initial velocity of $v_0 = -38m/s$ as it approaches a bat. The bat applies an average force F_{avg} that is much larger than the weight of the ball, and the ball departs from the bat with a final velocity of $v_f = +58m/s$.
 - (a) Determine the impulse applied to the ball by the bat.
 - (b) Assuming time of contact is $\Delta t = 1.6 \times 10^{-3} s$, find the average force exerted on the ball by the bat.

Solution

a)
$$J = mv_f - mv_0$$

$$= (0.14kg)(58m/s) - (0.14kg)(-38m/s)$$

$$:J = +13.4 \text{ kg.m/s}$$

(b)
$$F_{avg} = \frac{J}{\Delta t} = \frac{13.4 \text{kg.m/s}}{1.6 \times 10^{-3} \text{s}} = +8400 \text{N}$$

Note: Both the impulse applied to the ball and the average force are directed to the east



Exercise

An 3-kg ball strikes a wall with a speed of 10 *m/s* at an angle of $\theta = 60^{\circ}$ with the surface. It bounces off with the same speed and angle. If the ball is in contact with the wall for 0.2 *s*, what is the average force exerted by the wall on the ball?



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Impulse-Momentum Theory

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Soution
$$\vec{J} = m\vec{v}_2 - m\vec{v}_1$$
 $\vec{J} = \vec{F}_{avg}\Delta t$
 $\vec{F}_{avg}\Delta t = m\vec{v}_2 - m\vec{v}_1$
 $\vec{v}_1 = v_{1x}\hat{i} + v_{1y}\hat{j} = v_1\cos\theta\hat{i} + v_1\sin\theta\hat{j}$
 $\vec{v}_2 = v_{2x}\hat{i} + v_{2y}\hat{j} = -v_2\cos\theta\hat{i} + v_2\sin\theta\hat{j}$
 $\vec{v}_2 - \vec{v}_1 = (-v_2\cos\theta\hat{i} + v_2\sin\theta\hat{j}) - (v_1\cos\theta\hat{i} + v_1\sin\theta\hat{j})$
 $\therefore v_1 = v_2 = v$
 $m(\vec{v}_2 - \vec{v}_1) = m[(-v\cos\theta\hat{i} + v\sin\theta\hat{j}) - (v\cos\theta\hat{i} + v\sin\theta\hat{j})] = -2mv\cos\theta\hat{i}$
 $\vec{F}_{avg}\Delta t = -2mv\cos\theta\hat{i}$ or $\vec{F}_{avg} = \frac{-2mv\cos\theta\hat{i}}{\Delta t}$
 $v = 10 m/s, \theta = 60^\circ, \Delta t = 0.2 s$ $\Rightarrow \vec{F}_{avg} = \frac{-2(3kg)(10m/s)\cos6\theta}{0.2s}\hat{i} = -150\hat{i}N$



- Collision is any strong interaction between bodies that lasts a relatively short time
 - Car's collision
 - Balls colliding on a pool table
 - Neutrons hitting nuclei in reactor core
 - Bowling ball striking pins
- If the forces between the bodies are <u>much larger</u> than any <u>external</u> forces, we can neglect the external forces entirely and treat the bodies as *isolated system*
- Since a *collision* constitutes an isolated system (where the net external force is zero), the *momentum of the system is conserved* (the same before and after the collision)
- Collision types: *inelastic* and *elastic* collisions

Collisions











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(b)



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- In any collision in which external forces can be neglected, momentum is conserved and the total momentum before equals the total momentum after
- Collisions are classified according to how much energy is "lost" during the collision
- Inelastic Collisions there is a loss of kinetic energy due to the collision

•Automobile collision is <u>inelastic</u>: the structure of the car absorbs as much of the energy of collision as possible. This absorbed energy cannot be recovered, since it goes into a permanent deformation of the car

Completely Inelastic Collisions - the loss of kinetic energy is the maximum possible. The objects stick together after the collision.

Elastic collisions - the kinetic energy of the system is conserved

Completely (or perfectly) inelastic collision:

 Glider A and glider B approach each other on a frictionless surface

Each glider has a putty on the end, so gliders stick together after collision



(b)



(c)

A 10-g bullet is fired into a stationary block of wood Problem having mass m = 5 kg. The bullet imbeds into the block. speed of the bullet-plus-wood combination The immediately after the collision is 0.6 m/s. What was the original speed of the bullet? $V_{bullet+block} = V'_x = 0.6 m/s$ $v_{block} = v_{2x} = 0$ $v_{bullet} = v_{Ix} = ?$ $m_{block} = 5 \ kg$ $M_{bullet+block} = 5.01 \ kg$ $m_{bullet} = 10 \ g = 0.01 kg$

Before Collision

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Solution
Before Collision

$$m_1v_{1x} + m_2v_{2x} = m_1v'_{1x} + m_2v'_{2x}$$

 $v'_{1x} = v'_{2x} = V'_x$
 $m_1v_{1x} + m_2v_{2x} = (m_1 + m_2)V'_x$
 $m_{bullet}v_{bullet} + m_{block}v_{block} = (m_1 + m_2)V'_x$
 $m_{bullet} = 0.01kg$
 $m_{block} = 5 kg$
 $v_{bullet} = v_{1x} = ?$
 $v_{block} = v_{2x} = 0$
 $(0.01kg)v_{bullet} + 0 = (5.01kg)(0.6m/s)$
 $v_{bullet} = 300.6m/s$

Problem A 12-g wad of sticky clay is hurled horizontally at 100-g wooden block initially at rest on a horizontal surface (frictionless before impact). The clay sticks to the block. After impact, the block slides 7.5 *m* before coming to rest. If the coefficient of friction between the block and the surface is 0.65, what was the speed of the clay immediately before impact?



Solution

$$m_{1}v_{1x} + m_{2}v_{2x} = m_{1}v'_{1x} + m_{2}v'_{2x}$$
$$v'_{1x} = v'_{2x} = V'_{x} = ?$$
$$m_{clay}v_{clay} + m_{block}v_{block} = (m_{clay} + m_{block})V'_{x}$$

$$v_{block} = 0, v_{clay} = ?$$

$$(0.012kg)v_{clay} + 0 = (0.112kg)V'_{x} - - - -(1)$$





Problem

The ballistic pendulum consists of a block of wood (mass $m_2 = 2.5$ kg) suspended by a wire of negligible mass. A bullet (mass $m_1 = 0.01$ kg) is fired with a speed v_{01} . After collision, the block has a speed v_f and then swings to a maximum height of 0.65m above the initial position. Find the speed v_{01} of the bullet, assuming air resistance is negligible.



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Solution



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 $v_{01} = +896m/s$

Solution





Exercise A 90-kg fullback running east with a speed of 5 m/s is tackled by a 95-kg opponent running north with a speed of 3 m/s. (a) Explain why the successful tackle constitutes a perfectly inelastic collision. (b) Calculate the velocity of the players immediately after the tackle. (c) Determine the mechanical energy that disappears as a result of the collision. Account for the missing energy,

Elastic collision:

- Glider A and glider B approach each other on a frictionless surface
- Each glider has a steel spring bumper on the end to ensure an elastic collision





(b)



(c)

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Elastic 1-D collision of two bodies A and B, B is at rest before collision

- *Momentum* of the system is *conserved*
- *Kinetic energy* of the system is *conserved*

$$m_{A}v_{A1x} + m_{B}(0) = m_{A}v_{A2x} + m_{B}v_{B2x} - --(1)$$

$$\frac{1}{2}m_{A}v_{A1x}^{2} + \frac{1}{2}m_{B}(0)^{2} = \frac{1}{2}m_{A}v_{A2x}^{2} + \frac{1}{2}m_{B}v_{B2x}^{2} - -(2)$$

$$m_{B}v_{B2x}^{2} = m_{A}(v_{A1x}^{2} - v_{A2x}^{2}) = m_{A}(v_{A1x} - v_{A2x})(v_{A1x} + v_{A2x}) - -(3)$$
From equation (1), one can have
$$m_{B}v_{B2x} = m_{A}(v_{A1x} - v_{A2x}) - - - -(4)$$
Divide equations (3) by equation (4) to get
$$v_{B2x} = v_{A1x} + v_{A2x} - - -(5)$$
From equation (5) into equation (4) we can have
$$m_{B}(v_{A1x} + v_{A2x}) = m_{A}(v_{A1x} - v_{A2x}) - - - -(6)$$

$$v_{A2x} = \frac{m_{A} - m_{B}}{m_{A} + m_{B}}v_{A1x} - - - -(7)$$

From equation (7) into equation (5) one can have

$$v_{B2x} = \frac{2m_A}{m_A + m_B} v_{A1x} - - - - -(8)$$

$$v_{A2x} = \frac{m_A - m_B}{m_A + m_B} v_{A1x}$$

$$v_{B2x} = \frac{2m_A}{m_A + m_B} v_{A1x}$$

Remarks on some Cases of Elastic collision

- Suppose body A is a ping-pong ball, and body B is bowling ball
- We expect A to bounce of after the collision with almost the same speed but opposite direction, and speed of B will be much smaller
- > What if situation is reversed? Bowling ball hits ping-pong ball?



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$$v_{A2x} = \frac{m_A - m_B}{m_A + m_B} v_{A1x}$$

$$v_{B2x} = \frac{2m_A}{m_A + m_B} v_{A1x}$$

The case of equal masses

- Suppose masses of bodies A and B are equal
- Then $m_A = m_B$, and $V_{A2x} = 0$, $V_{B2x} = V_{A1x}$





$$v_{A2x} = \frac{m_A - m_B}{m_A + m_B} v_{A1x} \qquad \qquad v_{B2x} = \frac{2m_A}{m_A + m_B} v_{A1x}$$

Relative Velocities Before and After Collision

 $v_{B2x} = v_{A1x} + v_{A2x} \qquad \longrightarrow \qquad v_{B2x} - v_{A2x} = v_{A1x}$

- V_{B2x} - V_{A2x} is relative velocity of B to A after the collision, and it is <u>negative</u> of the velocity of B relative to A before the collision
- In a straight-line elastic collision of two bodies, the relative velocities before and after collision have the same magnitude, but opposite sign
- General case (when velocity of B is not zero):

$$v_{B2x} - v_{A2x} = -(v_{B1x} - v_{A1x})$$

Problem

A ball of mass $m_1 = 0.25$ kg and velocity $v_{01} = 5m/s$ collides head-on with a ball of mass $m_2 = 0.8$ kg that is initially at rest ($v_{02} = 0$). No external forces act on the balls. If the collision in elastic, what are the velocities of the balls after the collision?



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Solution





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Solution Substitute $v_{f_2} = \frac{2m_1}{m_1 + m_2} v_{0_1}$ into $m_1 v_{f_1} = m_1 v_{0_1} - m_2 v_{f_2} - --(1)$ $m_1 v_{f_1} = m_1 v_{0_1} - m_2 \frac{2m_1}{m_1 + m_2} v_{0_1}$ $m_1 v_{f_1} = m_1 \left(1 - \frac{2m_2}{m_1 + m_2} \right) v_{0_1}$ Before m_1 ₹01 v₀₂ = 0 m/s $m_1 v_{f_1} = m_1 \left| \frac{m_1 + m_2 - 2m_2}{m_1 + m_2} \right| v_{0_1}$ After $v_{f_1} = \left| \frac{m_1 - m_2}{m_1 + m_2} \right| v_{0_1}$ V D ۳n

We have
$$v_{f_2} = \frac{2m_1}{m_1 + m_2} v_{0_1}$$
 $v_{f_1} = \left[\frac{m_1 - m_2}{m_1 + m_2}\right] v_{0_1}$

 $m_1 = 0.25 \text{ kg}, m_2 = 0.8 \text{ kg}$

Solution

$$v_{01} = 5 \text{ m/s}, v_{02} = 0$$





$$v_{f_1} = \left(\frac{0.25 - 0.8}{0.25 + 0.8}\right) 5 = -2.62m/s$$

$$v_{f_2} = \frac{2 \times 0.25}{0.25 + 0.8} \times 5 = 2.38m/s$$

Exercise A ball of mass $m_1 = 1.5$ kg attached to a string is released with a speed of 5 m/s from the position shown at height h = 3 m above the horizontal. Another ball of mass $m_2 = 10$ kg, initially at rest, is attached to another string. Assuming the collision is elastic, (a) find the final velocities of the two balls immediately after collision. (b) Calculate the maximum heights to which m_1 and m_2 rise after the elastic collision.

Answer: (a)
$$v_{f1} = -2.83 \text{ m/s}, v_{f2} = +2.73 \text{ m/s}$$

(b) $h_{f1} = 0.409 \text{ m}, h_{f2} = 0.38 \text{ m}$
0.300 m
 5.00 m/s
4.60 kg

Problem Two blocks are free to slide along the frictionless, wooden track shown in the figure. The block of mass $m_1 = 5$ kg is released from the position shown at height h = 5 m above the flat part of the track. Protruding from its front end is the north pole of a strong magnet which repels the north pole of an identical magnet embedded in the back end of the block of mass $m_2 = 10$ kg, initially at rest. The two blocks never touch. Calculate the maximum height to which m_1 rises after the elastic collision.



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Solution

Mass m_1 is released from rest and falls down from a height h = 5 m: Apply conservation of mechanical energy

$$\Delta U + \Delta K = 0$$

- $m_1 gh + (\frac{1}{2}m_1v_{1b}^2 - \frac{1}{2}m_1v_{01}^2) = 0$
 $v_{2b} = 0, h = 5 m$
 $\Rightarrow m_1 gh = \frac{1}{2}m_1v_{1b}^2$

$$\Rightarrow v_{1b} = \sqrt{2gh} = \sqrt{2(9.8m/s^2)(5m)} = 10m/s$$



Mass m_1 with speed $v_{1b} = 10 m/s$ elastically collides with mass Solution m_2 which is at rest ($v_{2b} = 0$): Apply conservation of momentum $m_1v_{1b} + m_2v_{2b} = m_1v_{1a} + m_2v_{2a}$ But $m_1 = 5 \text{ kg}, m_2 = 10 \text{ kg}, v_{1b} = 10 \text{ m/s}, v_{2b} = 0$ $\therefore (5kg)(10m/s) + (10kg)(0) = (5kg)v_{1a} + (10kg)v_{2a} \qquad or \ v_{2a} = \frac{3 - v_{1a}}{2} - - -(1)$ Apply conservation of kinetic energy $\frac{1}{2}m_1v_{1b}^2 + \frac{1}{2}m_{2b}v_{2b}^2 = \frac{1}{2}m_1v_{1a}^2 + \frac{1}{2}m_2v_{2a}^2$ or $100 = v_{1a}^2 + 2v_{2a}^2 - -(2)$ $(5kg)(10m/s)^{2} + (10kg)(0) = (5kg)v_{1a}^{2} + (10kg)v_{2a}^{2}$ $\Rightarrow 3v_{1a}^2 - 6v_{1a} - 191 = 0$ From equation (1) into (2), one can get: $\Rightarrow v_{1a} = -7m/s$ Immediately before collision Immediately after collision $v_{1b} = 10 m/s$ $v_{2b} = 0$ v_{1a} v_{2a} m_1 m_1 m_2 m_2 Prof. Rashad Badran

Solution

For mass m_1 with speed $v_{1a} = -7 m/s$ goes up the frictionless track until it reaches a maximum height h' (with $v_{1f} = 0$): Apply conservation of mechanical energy

 $\Delta U + \Delta K = 0$

$$m_{1}gh' + \left(\frac{1}{2}m_{1}v_{1f}^{2} - \frac{1}{2}m_{1}v_{1a}^{2}\right) = 0$$

$$v_{1a} = -7 \text{ m/s}, v_{1f} = 0$$

$$\Rightarrow gh' + \left(0 - \frac{1}{2}v_{1a}^{2}\right) = 0$$

$$or \quad h' = \frac{v_{1a}^{2}}{2g} = \frac{(7m/s)}{2(9.8m/s^{2})} = 2.5m$$


Problem A billiard ball moving at 5 m/s strikes a stationary ball of the same mass. After the collision, the first ball moves at 4.33 m/s at an angle of 30° with respect to the original line of motion. Assuming an elastic collision (and ignoring friction and rotational motion), find the struck ball's velocity after the collision.



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Solution
$$(m_1\vec{v}_1 + m_2\vec{v}_2) = (m_1\vec{v}_1' + m_2\vec{v}_2')$$
 $m_1 = m_2 = m$
 $(v_{1x} + v_{2x}) = (v'_{1x} + v'_{2x})$ $(v_{1y} + v_{2y}) = (v'_{1y} + v'_{2y})$
 $v_{1x} = v_1, v_{2x} = 0, v'_{1x} = v'_1\cos\theta_1, v'_{2x} = v'_2\cos\theta_2, v_{1y} = v_{2y} = 0, v'_{1y} = v'_1\sin\theta_1, v'_{2y} = v'_2\sin\theta_2$
 $v_1 = v'_1\cos\theta_1 + v'_2\cos\theta_2$ $0 = v'_1\sin\theta_1 - v'_2\sin\theta_2$
 $5 = (4.33)\cos 30 + v'_2\cos\theta_2$ $0 = (4.33)\sin 30 - v'_2\sin\theta_2$
 $v'_2\cos\theta_2 = 1.25 - - - (1)$ $v'_2\sin\theta_2 = 2.165 - - - (2)$

Divide equation (2) by (1)

 $\tan \theta_2 = 2.165$ $\theta_2 = \tan^{-1}(1.73) = 60^{\circ}$

Substitute $\theta_2 = 60^\circ$ into equation (1)

$$v_2' = \frac{1.25}{\cos 60} = 2.5m/s$$



Conservation of Total Momentum

The executive stress reliever

This device illustrates laws of conservation of momentum and kinetic energy. As shown it consists of four identical hard balls supported by strings of equal lengths. When ball 1 is pulled and released after almost-elastic collision between it and ball 2, ball 1 stops and ball 4 moves out as shown.



Exercise: (a)Try to do your homework by explaining why balls 2 and 3 are at rest. (b) What is the velocity of ball 4 as it immediately leaves its position.





Consider *several particles* with masses m_1 , m_2 and so on.

- (x_1, y_1) are coordinates of m_1 , (x_2, y_2) are coordinates of m_2 .
- **Center of mass** of the system is the point having the coordinates (x_{cm}, y_{cm}) given by

$$x_{cm} = \frac{m_1 x_1 + m_2 x_2 + m_3 x_3 + \dots}{m_1 + m_2 + m_3 + \dots} = \frac{\sum_{i} m_i x_i}{\sum_{i} m_i}$$
$$y_{cm} = \frac{m_1 y_1 + m_2 y_2 + m_3 y_3 + \dots}{m_1 + m_2 + m_3 + \dots} = \frac{\sum_{i} m_i y_i}{\sum_{i} m_i}$$

□ The center of mass of a system of *N* particles with masses m_1 , m_2 , m_3 , etc. and positions, (x_1, y_1, z_1) , (x_2, y_2, z_2) , (x_3, y_3, z_3) , etc. is defined in terms of the particle's position vectors using

$$\vec{r}_{cm} = \frac{m_1 \vec{r}_1 + m_2 \vec{r}_2 + m_3 \vec{r}_3 + \dots}{m_1 + m_2 + m_3 + \dots} = \frac{\sum_i m_i \vec{r}_i}{\sum_i m_i}$$

- Center of mass is a *mass-weighted average position* of particles
- If this expression is differentiated with respect to time then the position vectors become velocity vectors and we have

$$\vec{v}_{cm} = \frac{m_1 \vec{v}_1 + m_2 \vec{v}_2 + m_3 \vec{v}_3 + \dots}{m_1 + m_2 + m_3 + \dots} = \frac{\sum_i m_i \vec{v}_i}{\sum_i m_i}$$



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$$\vec{v}_{cm} = \frac{m_1 \vec{v}_1 + m_2 \vec{v}_2 + m_3 \vec{v}_3 + \dots}{m_1 + m_2 + m_3 + \dots} = \frac{\sum_i m_i \vec{v}_i}{\sum_i m_i}$$

Total mass $M = m_1 + m_2 + m_3 + \dots$

$$M\vec{v}_{cm} = m_1\vec{v}_1 + m_2\vec{v}_2 + m_3\vec{v}_3 + \ldots = \vec{P}$$

Total moment of the system

• Total moment is equal to total mass times velocity of the center of mass

• For a system of particles on which the net external force is zero, so that the total momentum is constant, the velocity of the center of mass is also constant

> Spinning throwing knife on ice: center of mass follows straight line



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External Forces and Center-of-Mass Motion

- If we differentiate once again, then the derivatives of the velocity terms will be *accelerations*
- Further, if we use Netwon's Second Law for each particle then the terms of the form m_ia_i will be the net force on particle i.
- When these are summed over all particles any forces that are *internal* to the system (i.e. a force on particle *i* caused by particle *j*) will be <u>included in the sum twice</u> and these *pairs* will *cancel* due to Newton's Third Law. The result will be

$$M\vec{a}_{cm} = m_1\vec{a}_1 + m_2\vec{a}_2 + m_3\vec{a}_3 + \ldots = \sum \vec{F}_{ext}$$
 Body

Body or collection of particles

- It states that the *net external force* on a system of particles *equals* the *total mass* of the system *times* the *acceleration of the center of mass* (Newton's Second Law for a system of particles)
- It can also be expressed as the net external force on a system equals the time rate of change of the total linear momentum of the system.

The segmental method involves computation of the segmental *cm*'s The whole body *cm* is computed based on the segmental *cm*'s



Problem A water molecule consists of an oxygen atom with two hydrogen atoms bound to it. The angle between the two bounds is 106°. If the bounds are 0.1 *nm* long, where is the center of mass of the molecule?

Solution

$$\vec{r}_{cm} = \frac{m_1 \vec{r}_1 + m_2 \vec{r}_2 + m_3 \vec{r}_3 + \dots}{m_1 + m_2 + m_3 + \dots} = \frac{\sum_i m_i \vec{r}_i}{\sum_i m_i}$$

$$x_{cm} = \frac{m_1 x_1 + m_2 x_2 + m_3 x_3 + \dots}{m_1 + m_2 + m_3 + \dots} = \frac{\sum_i m_i x_i}{\sum_i m_i}$$

$$y_{cm} = \frac{m_1 y_1 + m_2 y_2 + m_3 y_3 + \dots}{m_1 + m_2 + m_3 + \dots} = \frac{\sum_i m_i y_i}{\sum_i m_i}$$

$$H$$

$$0.1 nm$$

$$0.1 nm$$

$$53^\circ$$

$$53^\circ$$

$$H$$

Problem A water molecule consists of an oxygen atom with two hydrogen atoms bound to it. The angle between the two bounds is 106°. If the bounds are 0.1 *nm* long, where is the center of mass of the molecule?

Solution

$$M_0 = 16u, M_H = 1u, x_{HL} = (-0.1)\sin 53), x_{HR} = (0.1)\sin 53)$$





Problem

Solution

A 2-kg particle has a velocity $\vec{v}_{2kg} = (2\hat{i} - 3\hat{j})m/s$ and a 3-kg particle has a velocity $\vec{v}_{3kg} = (1\hat{i} - 6\hat{j})m/s$ Find (a) the velocity of the center of mass and (b) the total momentum of the system.

(a)
$$\vec{v}_{cm} = \frac{m_1 \vec{v}_1 + m_2 \vec{v}_2 + m_3 \vec{v}_3 + \dots}{m_1 + m_2 + m_3 + \dots} = \frac{\sum_i m_i \vec{v}_i}{\sum_i m_i}$$

$$\vec{v}_{cm} = \frac{(2kg)(2\hat{i} - 3\hat{j})m/s + (3kg)(1\hat{i} - 6\hat{j})}{(2+3)kg} = \frac{7}{5}\hat{i} - \frac{24}{5}\hat{j}$$

(b)
$$\therefore M\vec{v}_{cm} = (2+3)(kg)(\frac{7}{5}\hat{i} - \frac{24}{5}\hat{j})m/s = (7\hat{i} - 24\hat{j})kg.m/s$$

Problem

Solution

During a time interval Δt a particle of mass m_1 is displaced along the x-axis by Δx_1 with a velocity v_1 , while another particle of mass m_2 is displaced by Δx_2 and with a velocity v_2 . Find (a) the displacement of the center of mass, and (b) the velocity of center of mass of the system. [Given $\Delta t = 0.2$ s, $\Delta x_1 = 4cm$, $\Delta x_2 = 2cm$, $m_1 = 2kg$, $m_1 = 3kg$]

(a)
$$\Delta x_{cm} = \frac{m_1 \Delta x_1 + m_2 \Delta x_2}{m_1 + m_2}$$

$$\Delta x_{cm} = \frac{(2kg)(4cm) + (3kg)(2cm)}{(2+3)kg} = 2.8cm$$
(b)
$$v_{cm} = \frac{m_1 v_1 + m_2 v_2}{m_1 + m_2}$$

$$|-\Delta x_1 - \lambda|$$

$$v_{cm} = \frac{(2kg)(20cm/s) + (3kg)(10cm/s)}{(2+3)kg} = 14cm/s$$