

Chapter 25 Ordinary Differential Equations (ODE's)

Runge-Kutta Methods

For a differential equation:

$$\frac{dy}{dx} = f(x, y)$$

$$dy = f(x, y) dx \Rightarrow \text{Integrate} \Rightarrow y(x) = \int f(x, y) dx$$

↗ function

25.1 Euler's Method

$$y_{i+1} = y_i + \frac{dy}{dx} h \quad , \quad y_{\text{new}} = y_{\text{old}} + (\text{slope}) (\text{Step size})$$

$$y_{i+1} = y_i + f(x_i, y_i) h \quad \text{Euler's Equation}$$

$$y_{i+1} = y(x_{i+1}), \quad y_i = y(x_i), \quad x_{i+1} = x_i + h$$

Example Use Euler's method to integrate

$$\frac{dy}{dx} = -2x^3 + 12x^2 - 20x + 8.5$$

from $x=0$ to $x=1$, use $h=0.5$, $y(0)=1$, $x_0=0$

Solution

$$y(x_{i+1}) = y(x_i) + f(x_i, y(x_i)) h$$

$$i=0 \quad y(x_1) = y(x_0) + f(x_0, y(x_0)) h$$

$$x_0 = 0 \\ x_1 = x_0 + h = 0.5$$

$$y(0.5) = y(0) + f(0, y(0)) h, \quad f(0, y(0)) = f(0, 1)$$

$$= 1 + (8.5)(0.5) \Rightarrow y(0.5) = 5.25$$

$$f(x, y) = \frac{dy}{dx} \Rightarrow \left. \frac{dy}{dx} \right|_{0,1} = 8.5$$

$$x_1 = 0.5, x_2 = x_1 + h = 1$$

$$i=1 \quad y(x_2) = y(x_1) + f(x_1, y(x_1))h$$

$$y(1) = y(0.5) + f(0.5, y(0.5))h, \quad f(0.5, 5.25)$$

$$= 5.25 + f(0.5, 5.25)h$$

$$= 5.25 + (1.25)(0.5) \Rightarrow \boxed{y(1) = 5.875}$$

$$\frac{dy}{dx} \Big|_{0.5, 5.25} = 1.25$$

For more details, see example 25.1 (Page 710) from your textbook

- Remember Taylor Series:

$$y_{i+1} = y_i + y'_i h + \frac{y''h^2}{2!} + \frac{y'''h^3}{3!} + \dots + \frac{y^{(n)}h^n}{n!} + R_n$$

\curvearrowright Remainder

$$\text{But, } y'_i = \frac{dy}{dx} = f(x_i, y_i)$$

Thus,

$$y_{i+1} = y_i + f(x_i, y_i)h + \frac{f'(x_i, y_i)h^2}{2} + \dots + \frac{f^{(n-1)}(x_i, y_i)h^n}{n!} + O(h^{n+1})$$

$$O(h^{n+1}) = \underbrace{\text{Local truncation error}}_{\begin{array}{l} \rightarrow \text{step size} \\ \downarrow n \end{array}}$$

$$\bullet \text{ Euler's equation} \Rightarrow y_{i+1} = y_i + f(x_i, y_i)h$$

$$\bullet \text{ True error } E_T = \text{true value} - \text{Approxi} \Rightarrow E_T = \underbrace{\frac{f'(x_i, y_i)h^2}{2} + \dots + O(h^{n+1})}_{\text{True local truncation error}}$$

$$E_A = \frac{f'(x_i, y_i)}{2} h^2$$

\leftarrow Approximate local truncation error

25.2 How to improve Euler's method ?

- Huen's method
- Mid-point method

Both methods above, require two steps to estimate the ODE solution (1- Predictor, 2- corrector)

* Huen's method

$$\frac{dy}{dx} = f(x, y)$$

Predictor :- ① $y_{i+1}^0 = y_i + f(x_i, y_i)h$

corrector ② $y_{i+1} = y_i + \frac{f(x_i, y_i) + f(x_{i+1}, y_{i+1}^0)}{2} h$

* Mid-point method

$$\frac{dy}{dx} = f(x, y)$$

Predictor ① $y_{i+\frac{1}{2}} = y_i + f(x_i, y_i) \frac{h}{2}$

② $y_{i+1} = y_i + f(x_{i+\frac{1}{2}}, y_{i+\frac{1}{2}}) h$

$$x_{i+\frac{1}{2}} = x_i + \frac{1}{2} h$$

Example $\frac{dy}{dx} = 4e^{0.8x} - 0.5y$, Integrate from $x=0$ to

$x=1$ using $h=1$ and $y(0)=2$ in

(a) Huen's method

(b) Mid-point method

Solution

(a) Huen's method

$$y_{i+1}^o = y_i + f(x_i, y_i)h$$

$$y_{i+1} = y_i + \frac{f(x_i, y_i) + f(x_{i+1}, y_{i+1}^o)}{2} h$$

i=0

$$y_1^o = y_0 + f(x_0, y_0)h$$

$$y(x_1) = y(x_0) + f(x_0, y(x_0))h, \quad x_0=0, x_1=x_0+h=1$$

$$y(1) = y(0) + f(0, y(0))h, \quad f(0, y(0)) = f(0, 2)$$

$$y(1) = 2 + 3(1) \Rightarrow \underbrace{y(1) = 5}_{y(1) = 5}, \quad f(0, 2) = 4e^{0.8(0)} - (0.5)(2)$$

$$y_1 = y_0 + \frac{f(x_0, y_0) + f(x_1, y_1^o)}{2} h = 3$$

$$y(x_1) = y(x_0) + \frac{f(x_0, y(x_0)) + f(x_1, y^o(x_1))}{2} h = y(1)$$

$$y(1) = y(0) + \frac{f(0, 2) + f(1, 5)}{2} h, \quad f(0, 2) = 4e^{0.8(0)} - (0.5)(2)$$

$$= 2 + \frac{3 + 6.4}{2} (1) \Rightarrow \boxed{y(1) = 6.701}$$

$$f(1, 5) = 4e^{0.8(1)} - (0.5)(1)$$

$$= 6.4$$

(b) Mid-point method

$$y_{i+\frac{1}{2}} = y_i + f(x_i, y_i) \frac{h}{2}$$

$$y_{i+1} = y_i + f(x_{i+\frac{1}{2}}, y_{i+\frac{1}{2}}) h$$

i=0

$$y_{\frac{1}{2}} = y_0 + f(x_0, y_0) \frac{h}{2}$$

$$y(x_{\frac{1}{2}}) = y(x_0) + f(x_0, y(x_0)) \frac{h}{2} \quad x_0 = 0, x_{\frac{1}{2}} = x_0 + \frac{h}{2} = 0.5$$

$$y(0.5) = y(0) + f(0, y(0)) \frac{h}{2}, y(0) = 2$$

$$= y(0) + f(0, 2) \frac{h}{2}$$

$$= 2 + (3)(\frac{1}{2}) \Rightarrow y(0.5) = 3.5$$

$$y_1 = y_0 + f(x_{\frac{1}{2}}, y_{\frac{1}{2}}) h$$

$$y(x_1) = y(x_0) + f(x_{\frac{1}{2}}, y(x_{\frac{1}{2}})) h \quad x_0 = 0, x_1 = x_0 + h = 1$$

$$y(1) = y(0) + f(0.5, y(0.5)) h, y(0.5) = 3.5$$

$$= y(0) + f(0.5, 3.5) h$$

$$= 2 + (4.22)(1) \Rightarrow y(1) = 6.22$$

$$f(0.5, 3.5) = 4e^{(0.8)(1)} - (0.5)(3.5)$$

$$= 4.22$$

Chapter 25: ODE's

25.3 Runge-Kutta methods (RK methods)

- First order RK (RK1) → Euler's method
- Second order RK (RK2)
- Third order RK (RK3)
- Fourth order RK (RK4)

* First order RK (RK1)

$$\frac{dy}{dx} = f(x, y)$$

$$y_{i+1} = y_i + k_1 h, \quad k_1 = f(x_i, y_i), \quad h = \text{step size}$$

Improvements

- Heun's
- Mid-point methods

* Second order RK (RK2)

$$\frac{dy}{dx} = f(x, y)$$

$$y_{i+1} = y_i + (a_1 k_1 + a_2 k_2) h$$

$$k_1 = f(x_i, y_i), \quad k_2 = f(x_i + p_1 h, y_i + q_{11} k_1 h)$$

a_1, a_2, p_1 and q_{11} ⇒ constants

$$a_1 + a_2 = 1 \quad \left. \begin{array}{l} \\ \end{array} \right\} \text{see Box 25.1 page 731 for more details}$$

$$a_2 p_1 = \frac{1}{2} \quad \left. \begin{array}{l} \\ \end{array} \right\} 3 \text{ equations and } 4 \text{ unknowns}$$

$$a_2 q_{11} = \frac{1}{2} \quad \Rightarrow \text{Assume } a_2 \text{ and find } a_1, p_1, \text{ and } q_{11}$$

* Huen's method ($\alpha_2 = \frac{1}{2}$)

$$\Rightarrow \alpha_1 = \frac{1}{2}, p_1 = 1, q_{11} = 1$$

$$\Rightarrow y_{i+1} = y_i + \frac{1}{2}(k_1 + k_2)h$$

$$k_1 = f(x_i, y_i), k_2 = f(x_i + h, y_i + k_1 h)$$

* Mid-point Method ($\alpha_2 = 1$)

$$\Rightarrow \alpha_1 = 0, p_1 = \frac{1}{2}, q_{11} = \frac{1}{2}$$

$$\Rightarrow y_{i+1} = y_i + k_2 h$$

$$k_2 = f(x_i + \frac{1}{2}h, y_i + \frac{1}{2}k_1 h), k_1 = f(x_i, y_i)$$

* Ralston's method ($\alpha_2 = \frac{2}{3}$)

$$\alpha_1 = \frac{1}{3}, p_1 = \frac{3}{4} \text{ and } q_{11} = \frac{3}{4}$$

$$\Rightarrow y_{i+1} = y_i + \frac{1}{3}(k_1 + 2k_2)h$$

$$k_1 = f(x_i, y_i), k_2 = f(x_i + \frac{3}{4}h, y_i + \frac{3}{4}k_1 h)$$

* Third order RK (RK3)

$$\frac{dy}{dx} = f(x, y)$$

$$y_{i+1} = y_i + \frac{1}{6} (k_1 + 4k_2 + k_3) h$$

$$k_1 = f(x_i, y_i), \quad k_2 = f(x_i + \frac{1}{2}h, y_i + \frac{1}{2}k_1 h)$$

$$k_3 = f(x_i + h, y_i - k_1 h + 2k_2 h)$$

* Fourth order RK (RK4)

$$\frac{dy}{dx} = f(x, y)$$

$$y_{i+1} = y_i + \frac{1}{6} (k_1 + 2k_2 + 2k_3 + k_4) h$$

$$k_1 = f(x_i, y_i), \quad k_2 = f(x_i + \frac{1}{2}h, y_i + \frac{1}{2}k_1 h)$$

$$k_3 = f(x_i + \frac{1}{2}h, y_i + \frac{1}{2}k_2 h), \quad k_4 = f(x_i + h, y_i + k_3 h)$$

Example : $f(x, y) = \frac{dy}{dx} = -2x^3 + 12x^2 - 20x + 8.5$

Solve the above ODE using RK4 from $x=0$ to $x=0.5$
Use $h = 0.5$ and $y(0) = 1$

Solution

$$i=0 \quad y_1 = y_0 + \frac{1}{6}(k_1 + 2k_2 + 2k_3 + k_4)h$$

$$y_0 = y(x_0) = y(0) = 1, \quad k_1 = f(x_0, y_0) = f(x_0, y(x_0)) = f(0, 1) = 8.5$$

$$\begin{aligned} k_2 &= f\left(x_0 + \frac{h}{2}, \tilde{y}_0^{y(x_0)} + \frac{1}{2}k_1 h\right) = f\left(0 + \frac{0.5}{2}, 1 + \frac{1}{2}(8.5)(0.5)\right) \\ &= f(0.25, 3.125) = 4.22, \quad \underbrace{k_2 = 4.22}_{\text{in cloud}} \end{aligned}$$

$$\begin{aligned} k_3 &= f\left(x_0 + \frac{1}{2}h, \tilde{y}_0^{y(x_0)} + \frac{1}{2}k_2 h\right) = f\left(0 + \frac{1}{2}(0.5), 1 + \frac{1}{2}(4.22)(0.5)\right) \\ &= f(0.25, 2.06) \Rightarrow \underbrace{k_3 = 4.22}_{\text{in cloud}} \end{aligned}$$

$$\begin{aligned} k_4 &= f(x_0 + h, \tilde{y}_0^{y(x_0)} + k_3 h) = f(0.5, 1 + (4.22)(0.5)) \\ &= f(0.5, 3.11) \Rightarrow \underbrace{k_4 = 3.11}_{\text{in cloud}} \end{aligned}$$

$$\Rightarrow y(x_1) = y(x_0) + \frac{1}{6}(k_1 + 2k_2 + 2k_3 + k_4)h$$

$$\begin{aligned} y(0.5) &= y(0) + \frac{1}{6}(8.5 + (2)(4.22) + (2)(4.22) + 3.11)(0.5) \\ &\quad \underbrace{y(0.5) = 3.22}_{\text{in cloud}} \end{aligned}$$

Chapter 25 ODE's

25.4 Systems of Equations

A system of ODE's can be represented as:

$$\frac{dy_1}{dx} = f_1(x, y_1, y_2, \dots, y_n)$$

$$\frac{dy_2}{dx} = f_2(x, y_1, y_2, \dots, y_n)$$

⋮

$$\frac{dy_n}{dx} = f_n(x, y_1, y_2, \dots, y_n)$$

- To solve such kind of problems, we need (n) initial conditions
- We can apply all methods we have learnt previously to solve such system. However, for each y , we need a complete solution
- Euler's method

$$\frac{dy_1}{dx} = f_1(x, y_1, y_2) \quad , \quad \frac{dy_2}{dx} = f_2(x, y_1, y_2)$$

For each y , we need a rule, like

$$y_1(x_{i+1}) = y_1(x_i) + f_1(x_i, y_1(x_i), y_2(x_i)) h$$

$$y_2(x_{i+1}) = y_2(x_i) + f_2(x_i, y_1(x_i), y_2(x_i)) h$$

* This can also be applied in all RK methods, like
let's take RK3, for example

$$\frac{dy_1}{dx} = f_1(x, y_1, y_2, \dots, y_n) \quad \dots \quad \frac{dy_n}{dx} = f_n(x, y_1, y_2, \dots, y_n)$$

RK3

$$y_1(x_{i+1}) = y_1(x_i) + \frac{1}{6} (k_{1,1} + 4k_{2,1} + k_{3,1}) h$$

$$y_2(x_{i+1}) = y_2(x_i) + \frac{1}{6} (k_{1,2} + 4k_{2,2} + k_{3,2}) h$$

:

$$y_n(x_{i+1}) = y_n(x_i) + \frac{1}{6} (k_{1,n} + 4k_{2,n} + k_{3,n}) h$$

k_{ij} $\begin{cases} i & (1, 2, 3) \\ j & (1, 2, \dots, n) \end{cases}$

$$k_{1,1} = f_1(x, y_1(x_i), y_2(x_i), \dots, y_n(x_i))$$

$$k_{1,2} = f_2(x, y_1(x_i), y_2(x_i), \dots, y_n(x_i))$$

:

$$k_{1,n} = f_n(x, y_1(x_i), y_2(x_i), \dots, y_n(x_i))$$

$$k_{2,1} = f_1(x_i + \frac{1}{2}h, y_1(x_i) + \frac{1}{2}k_{1,1}h, y_2(x_i) + \frac{1}{2}k_{1,2}h, \dots, y_n(x_i) + \frac{1}{2}k_{1,n}h)$$

$$k_{2,2} = f_2(x_i + \frac{1}{2}h, y_1(x_i) + \frac{1}{2}k_{1,1}h, y_2(x_i) + \frac{1}{2}k_{1,2}h, \dots, y_n(x_i) + \frac{1}{2}k_{1,n}h)$$

:

$$k_{2,n} = f_n(x_i + \frac{1}{2}h, y_1(x_i) + \frac{1}{2}k_{1,1}h, y_2(x_i) + \frac{1}{2}k_{1,2}h, \dots, y_n(x_i) + \frac{1}{2}k_{1,n}h)$$

$$k_{3,1} = f_1(x_i + h, y_1(x_i) - k_{1,1}h + 2k_{2,1}h, \dots, y_n(x_i) - k_{1,n}h + 2k_{2,n}h)$$

$$k_{3,2} = f_2(x_i + h, y_1(x_i) - k_{1,1}h + 2k_{2,1}h, \dots, y_n(x_i) - k_{1,n}h + 2k_{2,n}h)$$

:

$$k_{3,n} = f_n(x_i + h, y_1(x_i) - k_{1,1}h + 2k_{2,1}h, \dots, y_n(x_i) - k_{1,n}h + 2k_{2,n}h)$$

Practice problem : For the system of ODE's we discussed, Please write the general soltn for y_i ($i=1, 2, \dots, n$) using the methods we discussed

1 - Euler's rule

- 1.1 - Euler's with Huen's method
- 1.2 - Euler's with Mid point

2 - RK 2

- RK 2 with Huen's method
- RK 2 with mid-point method
- RK 2 with Ralston's method

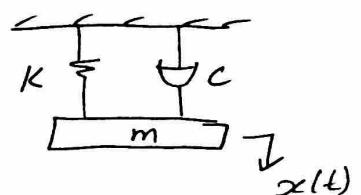
3 - RK 3 (Already done)

4 - RK 4

- * In real-life applications, we commonly have higher order ODE's
- * Till now, we only discussed first order ODE's
- * To solve higher order ODE's, we need to transform them to system of 1st order ODE's

Example For a spring-mass-damper system vibration, the governing equation is

$$m \ddot{x} + c\dot{x} + kx = 0, \quad \ddot{x} = \frac{d^2x}{dt^2}, \quad \dot{x} = \frac{dx}{dt}$$



To transform this second order ODE to system of 1st order ODE's:

$$y = \frac{dx}{dt} \Rightarrow \frac{dy}{dt} = \frac{d^2x}{dt^2}$$

$$\Rightarrow m \frac{dy}{dt} + cy + kx = 0 \Rightarrow \frac{dy}{dt} = - \frac{cy + kx}{m}$$

\Rightarrow System of ODE's become

$$\frac{dx}{dt} = f_1(t, y_1, x)$$

$$\frac{dy_1}{dt} = f_1(x, y_1, y_2), \quad \begin{matrix} t \\ y_1 \\ x \end{matrix}$$

$$\frac{dy_2}{dt} = f_2(t, y_2, x)$$

now, we can solve for y and x . (y_1, y_2)

we need to initial conditions to solve (will be given)