

* Transverse Vibrations of Beams - Ch 11

11.1

- 1- Euler-Bernoulli beam theory (only bending deformation) → we will deal with this.
- 2- Timoshenko beam theory (Bending and shear deformation)

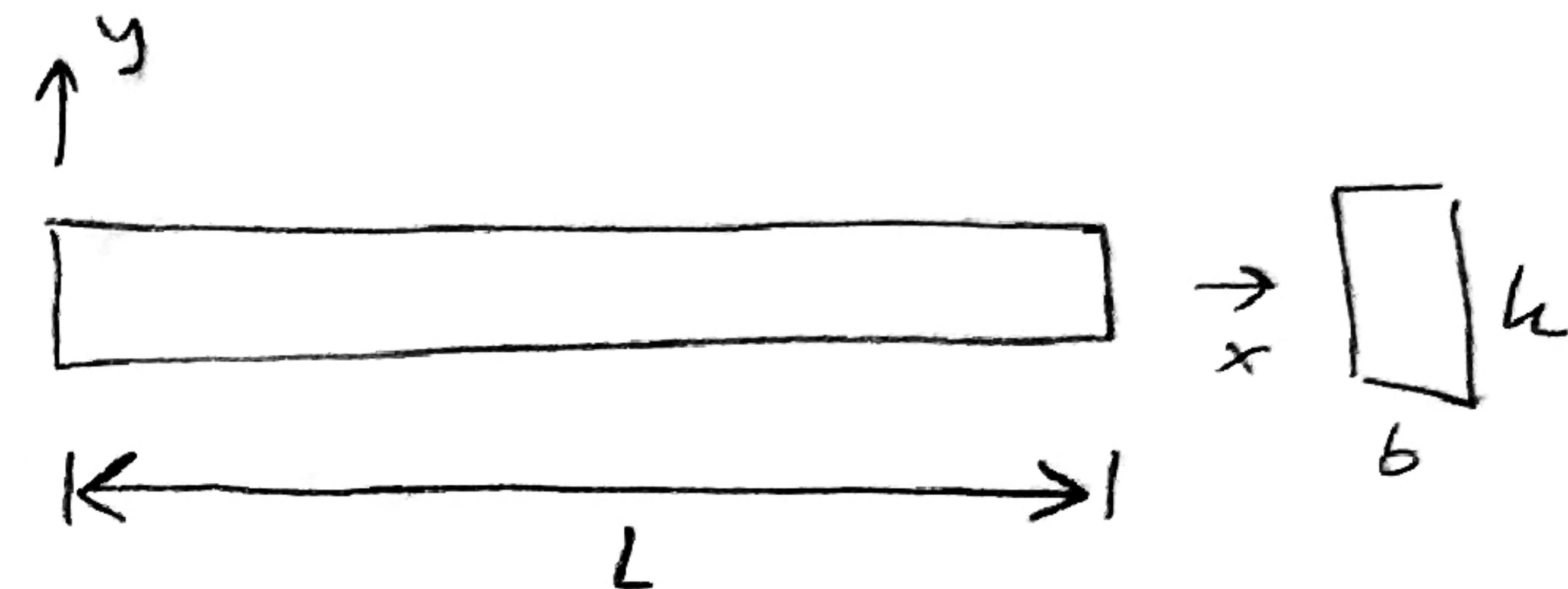
* Euler-Bernoulli beam theory assumptions

① $L \gg b, h$ by ten times

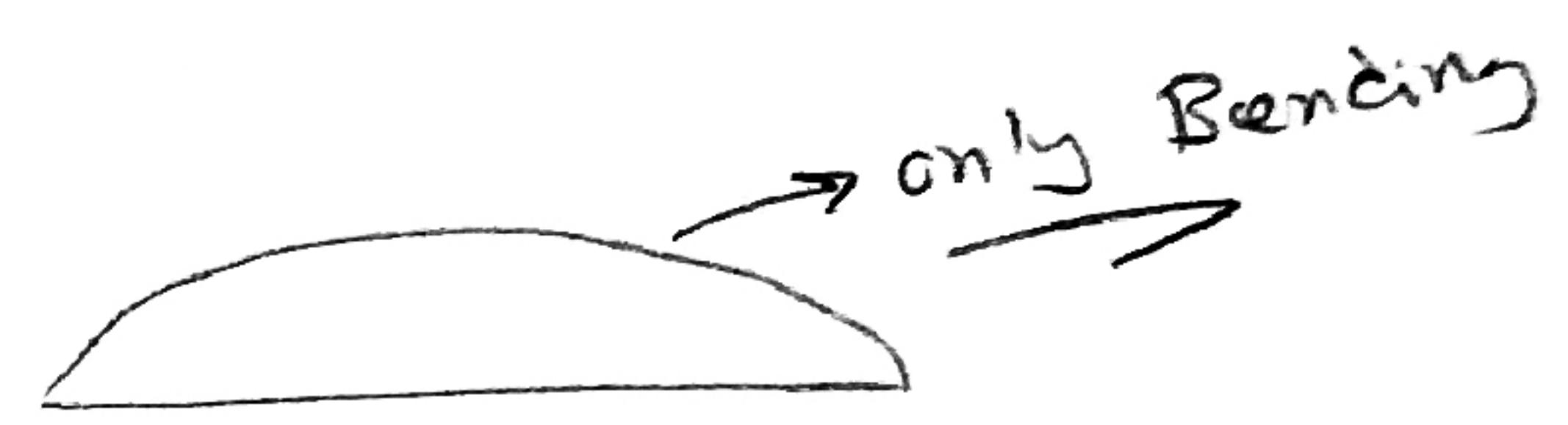
② Deflections are too small compared to the beam length (L)

③ Deflection function $\omega(x)$ and time (t) is $w(x, t)$.

④ Plane section remains plane.



L : length, b : width, h : height



11.2

* Kinetic energy and potential Energy:

$$T = \frac{1}{2} \int_0^L \rho A \dot{w}^2(x, t) dx$$

$$\dot{w}(x, t) = \frac{\partial w}{\partial t}$$

$$V = \frac{1}{2} \int_0^L EI w_{xx}^2(x, t) dx$$

$$w_{xx}^{(x)} = \frac{\partial^2 w}{\partial x^2}$$

ρ : Density (kg/m^3)

E : Elastic Modulus (Pa)

A : cross-sectional area ($bh = A$) [m^2]

I : Moment of Inertia about centroid [m^4] = $\frac{1}{12} bh^3$

Equation of motion (conservative system - no damping or forces) ②

$$\rho A \ddot{w}(x,t) + EI w_{xx}(x,t) = 0$$

$$\ddot{w} = \frac{\partial^2 w}{\partial t^2}$$

$$w_{xxx} = \frac{\partial^4 w}{\partial x^4}$$

* Non-conservative system

$$\rho A \ddot{w} + EI w_{xxx} + C \dot{w} = F(t)$$

* Boundary conditions

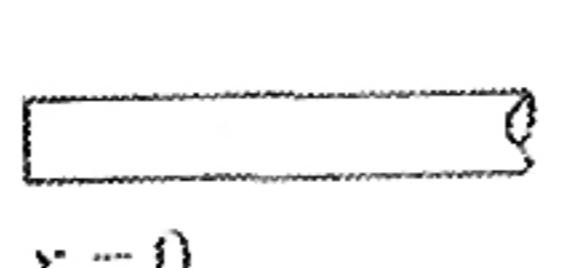
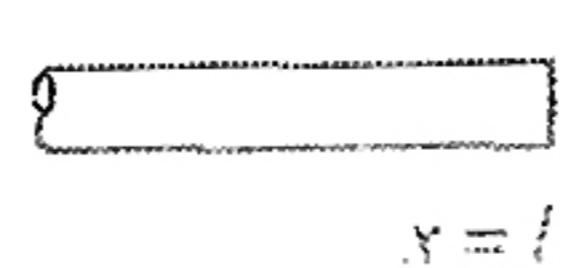
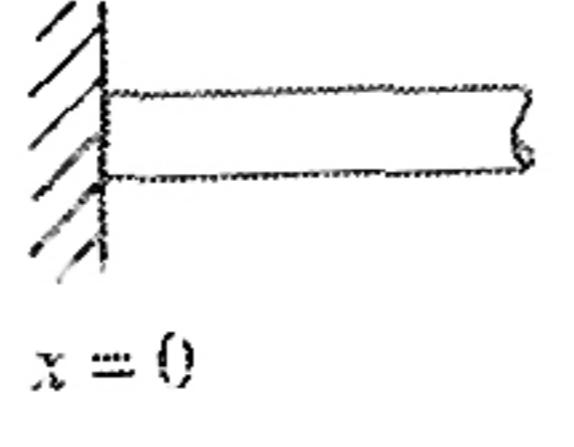
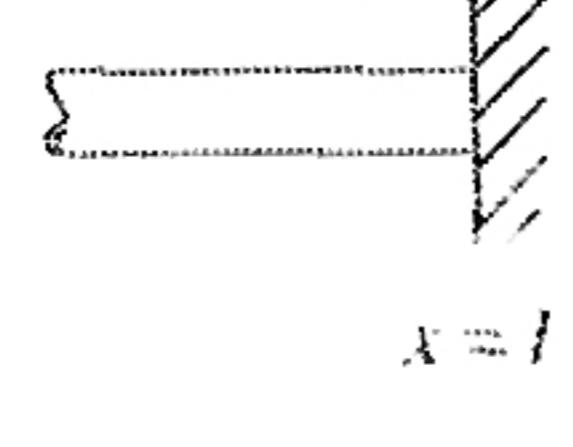
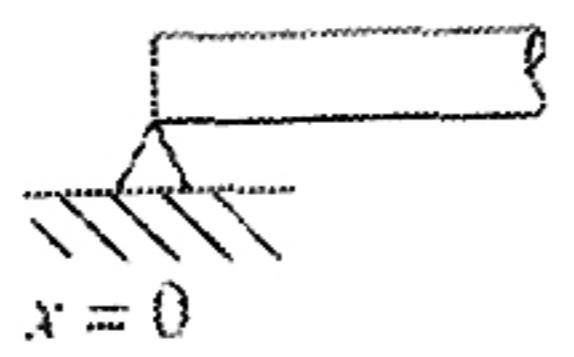
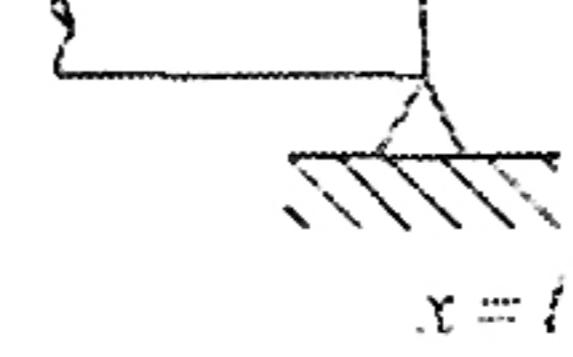
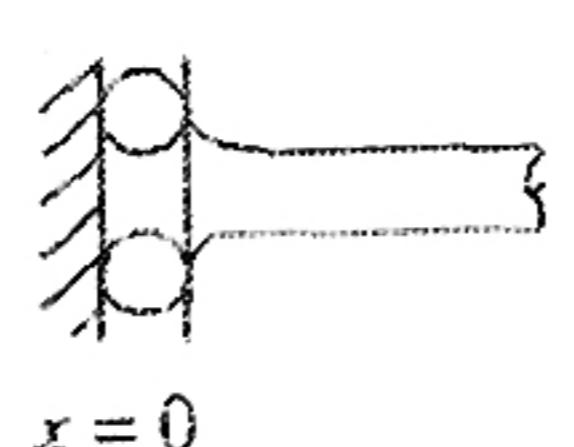
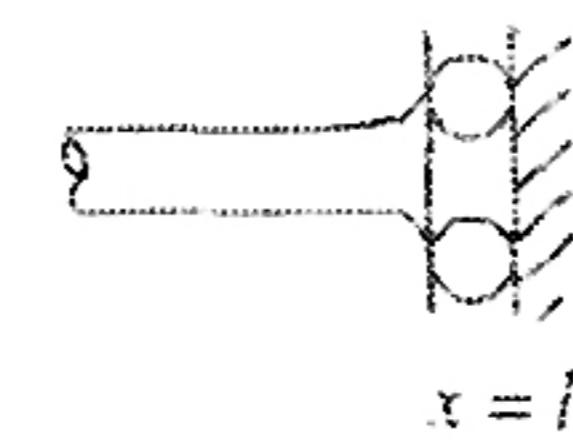
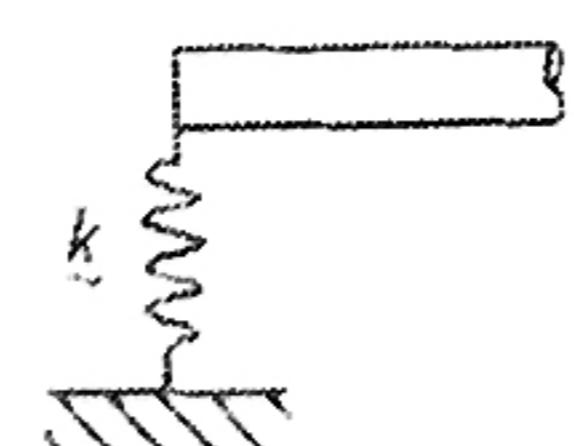
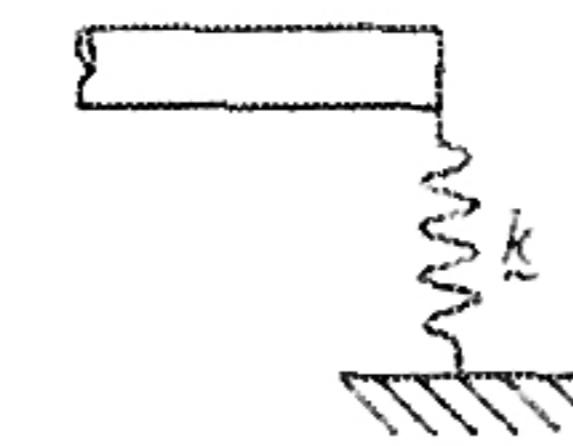
Initial conditions

$$w(x,0) = w_0$$

$$\dot{w}(x,0) = \dot{w}_0$$

Table 11.1 - textbook ① Page 323.

Table 11.1 Boundary Conditions of a Beams[†]

Boundary condition	At left end ($x = 0$)	At right end ($x = l$)
1. Free end (bending moment = 0, shear force = 0)	 $EI \frac{\partial^2 w}{\partial x^2}(0,t) = 0$ $\frac{\partial}{\partial x} \left(EI \frac{\partial^2 w}{\partial x^2} \right) \Big _{(0,t)} = 0$	 $EI \frac{\partial^2 w}{\partial x^2}(l,t) = 0$ $\frac{\partial}{\partial x} \left(EI \frac{\partial^2 w}{\partial x^2} \right) \Big _{(l,t)} = 0$
2. Fixed end (deflection = 0, slope = 0)	 $w(0,t) = 0$ $\frac{\partial w}{\partial x}(0,t) = 0$	 $w(l,t) = 0$ $\frac{\partial w}{\partial x}(l,t) = 0$
3. Simply supported end (deflection = 0, bending moment = 0)	 $w(0,t) = 0$ $EI \frac{\partial^2 w}{\partial x^2}(0,t) = 0$	 $w(l,t) = 0$ $EI \frac{\partial^2 w}{\partial x^2}(l,t) = 0$
4. Sliding end (slope = 0, shear force = 0)	 $\frac{\partial w}{\partial x}(0,t) = 0$ $\frac{\partial}{\partial x} \left(EI \frac{\partial^2 w}{\partial x^2} \right) \Big _{(0,t)} = 0$	 $\frac{\partial w}{\partial x}(l,t) = 0$ $\frac{\partial}{\partial x} \left(EI \frac{\partial^2 w}{\partial x^2} \right) \Big _{(l,t)} = 0$
5. End spring (spring constant = k)	 $\frac{\partial}{\partial x} \left(EI \frac{\partial^2 w}{\partial x^2} \right) \Big _{(0,t)} = -kw(0,t)$ $EI \frac{\partial^2 w}{\partial x^2}(0,t) = 0$	 $\frac{\partial}{\partial x} \left(EI \frac{\partial^2 w}{\partial x^2} \right) \Big _{(l,t)} = kw(l,t)$ $EI \frac{\partial^2 w}{\partial x^2}(l,t) = 0$

(continued overleaf)

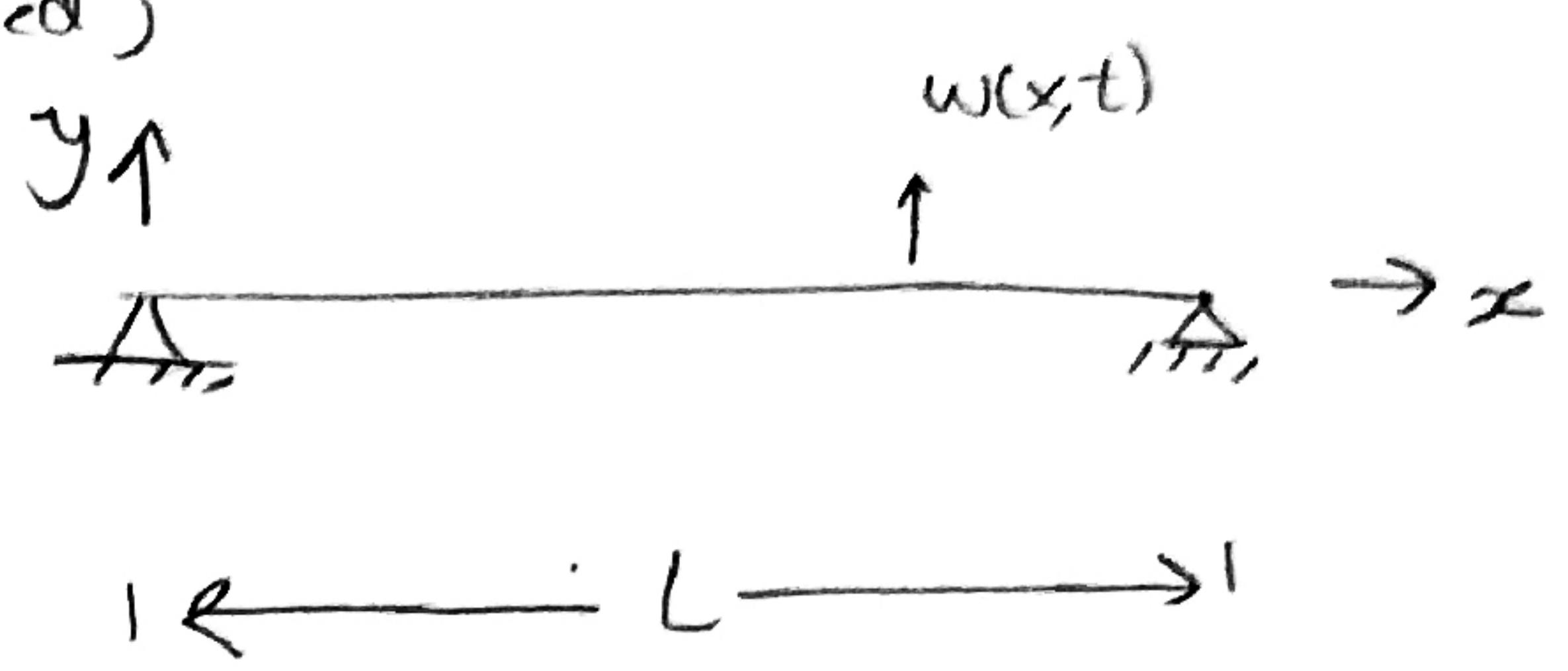
③

* Boundary conditions for common beam types:

① Simply-Supported Beams (Pinned-Pinned)

$$w(0, t) = w(l, t) = 0$$

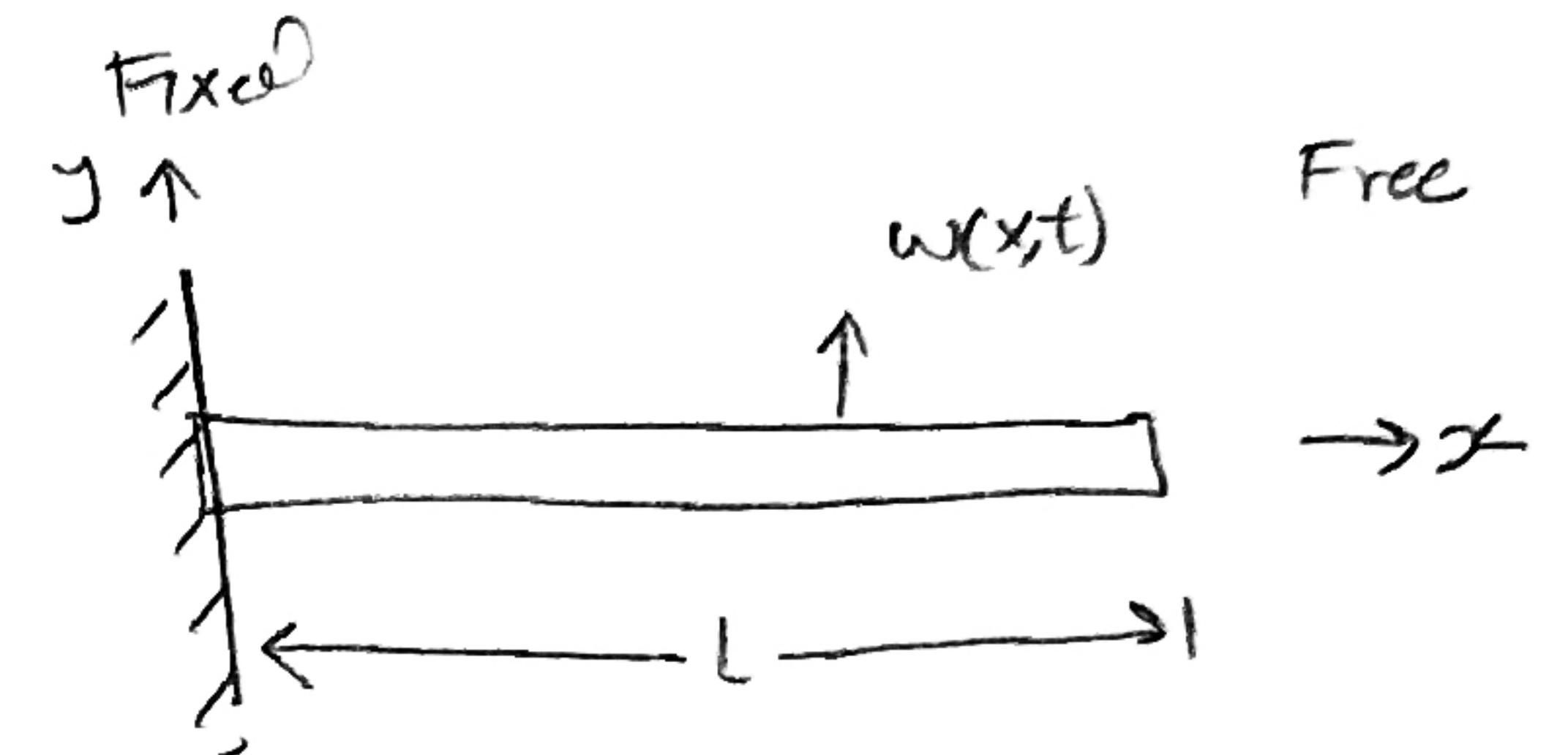
$$w_{xx}(0, t) = w_{xx}(l, t) = 0 \quad w_{xx} = \frac{\partial^2 w}{\partial x^2}$$



② Cantilever Beam (Fixed-Free)

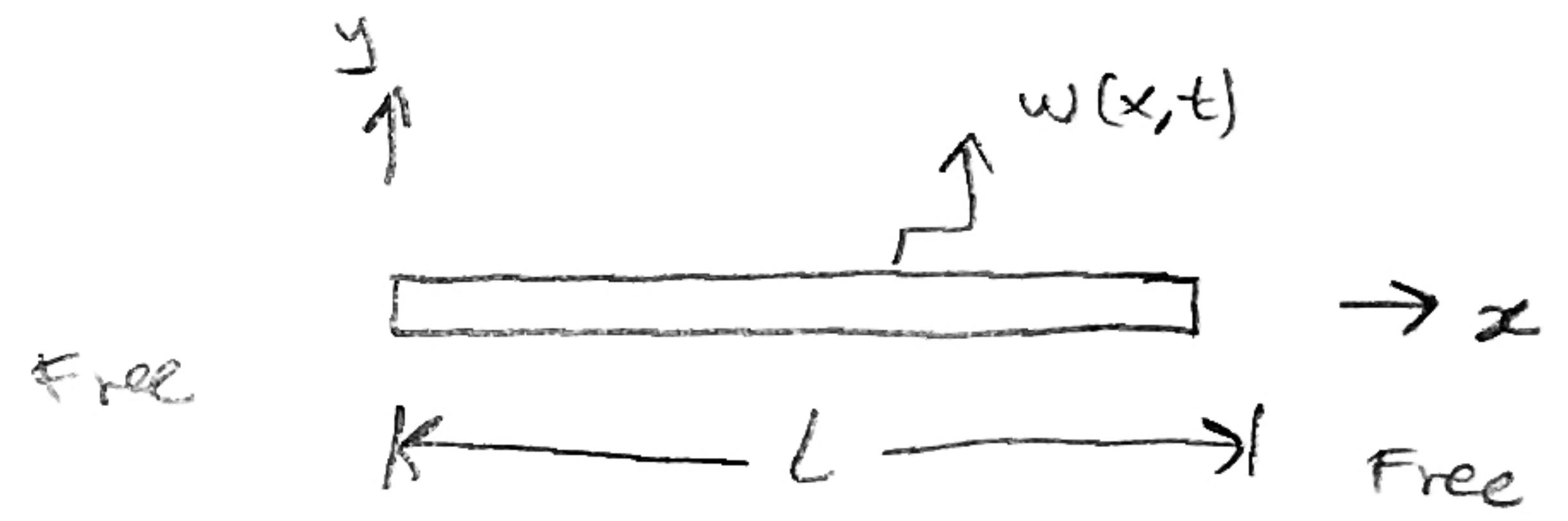
$$w(0, t) = 0, \quad w_x(0, t) = 0 \quad \text{Fixed end}$$

$$w_{xx}(l, t) = 0, \quad w_{xxx}(l, t) = 0 \quad \text{Free end}$$



③ Free-Free beam

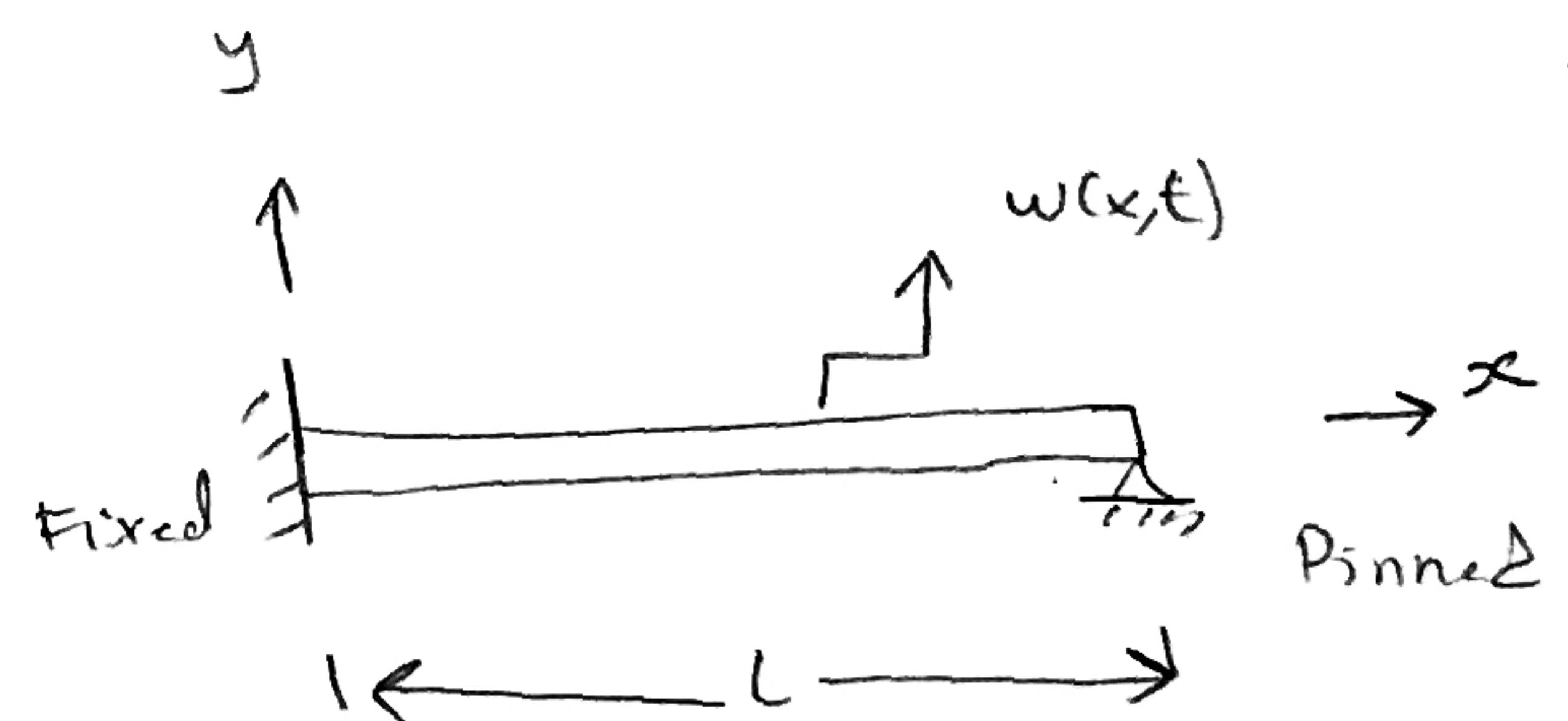
$$w_{xx}(0, t) = w_{xx}(l, t) = 0$$



④ Pinned-Fixed beam

$$w(0, t) = w_x(0, t) = 0 \quad \text{Fixed end}$$

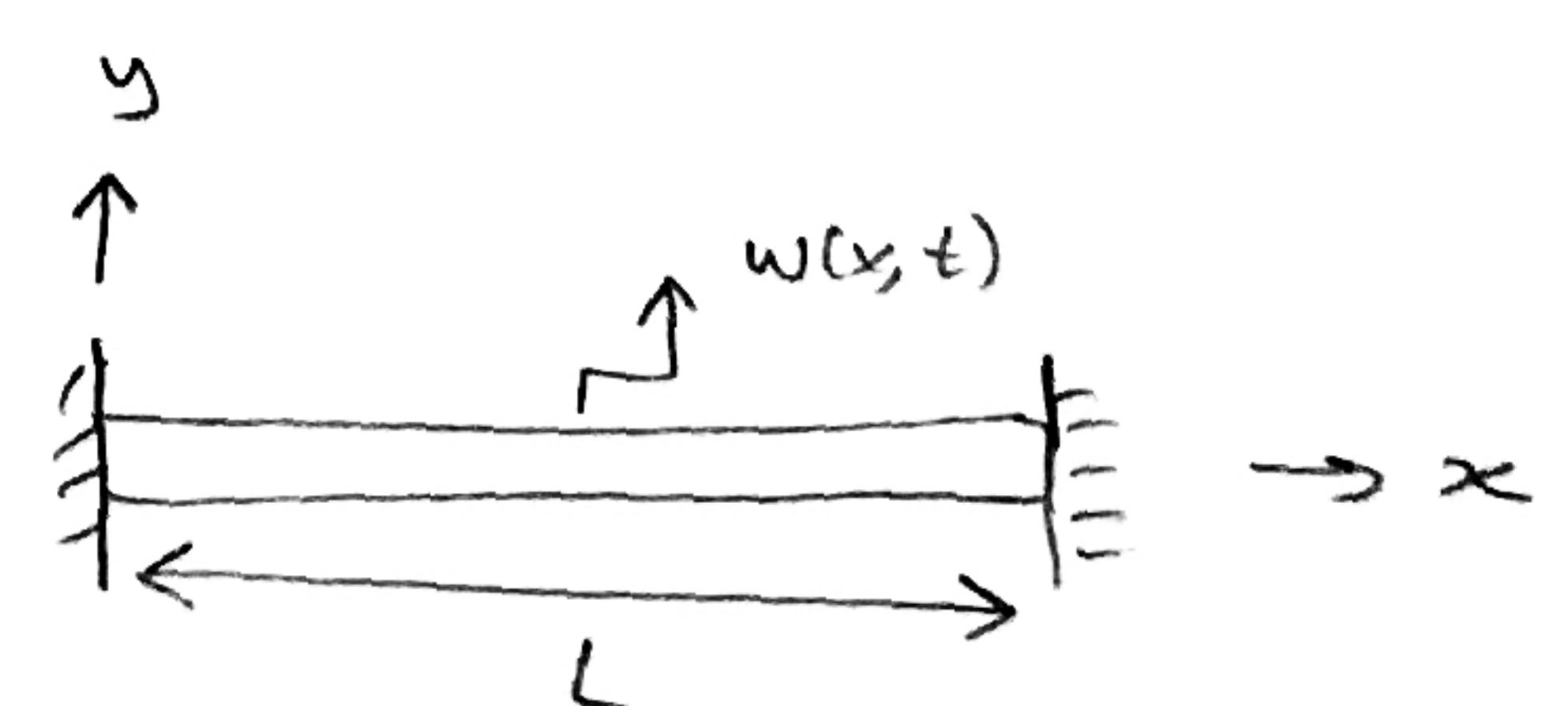
$$w(l, t) = w_{xx}(l, t) = 0 \quad \text{Pinned end}$$



⑤ Fixed-Fixed Beams (Clamped-Clamped)

$$w(0, t) = w(l, t) = 0$$

$$w_x(0, t) = w_x(l, t) = 0$$



(4)

11.4 Free vibration soln

$$EI \omega_{xxxx} + \rho A \ddot{w} = 0 \quad \text{-(1) Partial Differential equation (PDE)}$$

separation of variables

$$w(x,t) = X(x)\eta(t) \quad \leftarrow \text{Substitute in Eq(1)}$$

$$EI \phi_{xxxx}^{(x)} \eta(t) + \rho A \phi(x) \ddot{\eta}(t) = 0$$

$$\frac{\ddot{\eta}}{\eta} = - \frac{EI}{\rho A} \cdot \frac{\phi_{xxxx}}{\phi} = -\omega^2 \quad \begin{matrix} \text{"omega"} \\ \text{constant} \rightarrow \text{to get harmonic solution} \end{matrix}$$

$$\text{let } C^2 = \frac{EI}{\rho A}$$

$$\frac{\ddot{\eta}}{\eta} = -C^2 \frac{\phi_{xxxx}}{\phi} = -\omega^2$$

$$\Rightarrow \ddot{\eta} + \omega^2 \eta = 0 \quad \Rightarrow \eta(t) = A \cos \omega t + B \sin \omega t \quad \begin{matrix} A \text{ from IC's} \\ B \text{ from IC's} \end{matrix}$$

$$\phi_{xxxx}^{(x)} - \left(\frac{\omega}{C}\right)^2 \phi = 0$$

let

$$P^4 = \left(\frac{\omega}{C}\right)^2 = \omega^2 \frac{\rho A}{EI}$$

$$\omega = \sqrt{\frac{P^2}{C^2} \frac{EI}{\rho A}}$$

Depends on BC's

$$\phi(x) = a e^{rx} \quad \text{in Eq(2)}$$

$$r^4 - P^4 = 0 \quad \Rightarrow \quad r_{1,2} = \pm P$$

$$r_{3,4} = \pm i P$$

$$\phi(x) = A e^{rx} + B e^{-rx} + C e^{ix} + D e^{-ix}$$

or

$$\phi(x) = a \cos(px) + b \sin(px) + c \cosh(px) + d \sinh(px)$$

a, b, c, d

From

BC's

Mode shape

$$w(x,t) = \sum_{i=1}^n \phi_i(x) \eta_i(t)$$

$$\phi_i(x) = a_i \cos(p_i x) + b_i \sin(p_i x) + c_i \cosh(p_i x) + d_i \sinh(p_i x)$$

$$\eta_i(t) = A_i \omega_s w_i t + B_i \sin \omega_i t$$

Natural Frequencies and mode shapes

(5)

11.5.1 Simply-Supported (Pinned-Pinned) Beam

$$\text{EOM} \quad EI \ddot{w}_{xxxx} + \rho A \ddot{w} = 0$$

$$\text{BC's} \quad w(0,t) = w(l,t) = 0$$

$$w_{xx}(0,t) = w_{xx}(l,t) = 0$$

Find Nat. freq and modeshapes

$$w(x,t) = \phi(x) \eta(t)$$

$$\Rightarrow \phi(x) = a \cos(px) + b \sin(px) + c \cosh(px) + d \sinh(px)$$

$$\eta(t) = A \cos \omega t + B \sin \omega t$$

$$P^4 = \left(\frac{C}{\omega}\right)^2, \quad C^2 = \frac{\rho A}{EI}$$

BC's

$$w(0,t) = \phi(0) \eta(t) = 0 \Rightarrow \phi(0) = 0$$

$$w(l,t) = \phi(l) \eta(t) = 0 \Rightarrow \phi(l) = 0$$

$$w_{xx}(0,t) = \phi_{xx}(0) \eta(t) = 0 \Rightarrow \phi_{xx}(0) = 0$$

$$w_{xx}(l,t) = \phi_{xx}(l) \eta(t) = 0 \Rightarrow \phi_{xx}(l) = 0$$

$$\phi(0) = 0 = a \cos(0) + b \sin(0) + c \cosh(0) + d \sinh(0)$$

$$a + c = 0 \quad - \textcircled{*}$$

$$\phi_x(l) = -p a \sin(px) + p b \cos(px) + p c \sinh(px) + p d \cosh(px)$$

$$\phi_{xx}(x) = -p^2 a \cos(px) - p^2 b \sin(px) + p^2 c \cosh(px) + p^2 d \sinh(px)$$

$$\phi_{xx}(l) = -p^2 a + p^2 c = 0 \rightarrow \textcircled{*}$$

From Equati $\textcircled{*}$ and $\textcircled{*}$ $a = c = 0$

$$\phi(x) = b \sin(px) + d \sinh(px)$$

$$\phi(l) = 0 = b \sin pl + d \sinh(l)$$

$$\phi_{xx}(l) = 0 = -p^2 b \sin(pl) + p^2 d \sinh(l)$$

$$\begin{bmatrix} \sin pl & \sinh l \\ 0 & 0 \end{bmatrix} \begin{Bmatrix} b \\ d \end{Bmatrix} = \begin{Bmatrix} 0 \\ 0 \end{Bmatrix}$$

Mix Form

(6)

$$\begin{bmatrix} \text{Simple } & \sinh(\rho l) \\ -\text{Simple } & \sinh(\rho l) \end{bmatrix} \begin{Bmatrix} b \\ d \end{Bmatrix} = \begin{Bmatrix} 0 \\ 0 \end{Bmatrix}$$

only true if $b=d=0$ \times No solution

or $\det[] = 0 \Rightarrow \sin(\rho l) \sinh(\rho l) = 0$

or $\boxed{\sin(\rho l) = 0} \Rightarrow \rho l = n\pi \Rightarrow \boxed{P_n = \frac{n\pi}{l}}$

$\sinh(\rho l) = 0$

\hookrightarrow only true if $\rho l = 0$ or $\rho = 0$ \times No solution $P \neq 0$

Remember $P^4 = \left(\frac{\omega}{C}\right)^2 \Rightarrow \omega = P^2 \sqrt{\frac{EI}{PA}}$ or $\omega = (Pl)^2 \sqrt{\frac{EI}{JAl^4}}$

$\Rightarrow \boxed{\omega_n = (n\pi) \sqrt{\frac{EI}{JAl^4}}}$ natural frequency for each mode
for simply supported beam

Back to $\phi(x) = \underbrace{b \sin(\rho x)}_{=0} + \underbrace{d \sinh(\rho x)}_{=0}$

$\phi(x) = b \sin(\rho x)$

or $\phi_n(x) = b_n \sin\left(\frac{n\pi}{l}x\right)$

$P_n = \frac{n\pi}{l}$

In general $b_n = 1$ (Normalized mode shape)

$\phi_n(x) = \sin\left(\frac{n\pi}{l}x\right) \leftarrow$ Mode shape of simply-supported beam

Simply-Supported Beam

$$EIw_{xxxx} + \rho A \ddot{w} = 0$$

$$w(0, t) = w(l, t) = 0$$

$$w_{xx}(0, t) = w_{xx}(l, t) = 0$$

$$\Rightarrow \omega_n = \left(\frac{n\pi}{L}\right)^2 \sqrt{\frac{EI}{\rho A L^4}} \quad n = 1, 2, \dots, n \quad \Rightarrow \omega_n = (n\pi)^2 \sqrt{\frac{EI}{\rho A L^4}}$$

$$\phi(x) = \sin(p_n x) \Rightarrow \phi_n(x) = \sin(p_n x), \quad p_n = \frac{n\pi}{L}$$

$$\phi_n(x) = \sin\left(\frac{n\pi x}{L}\right)$$

First mode shape ($n=1$)

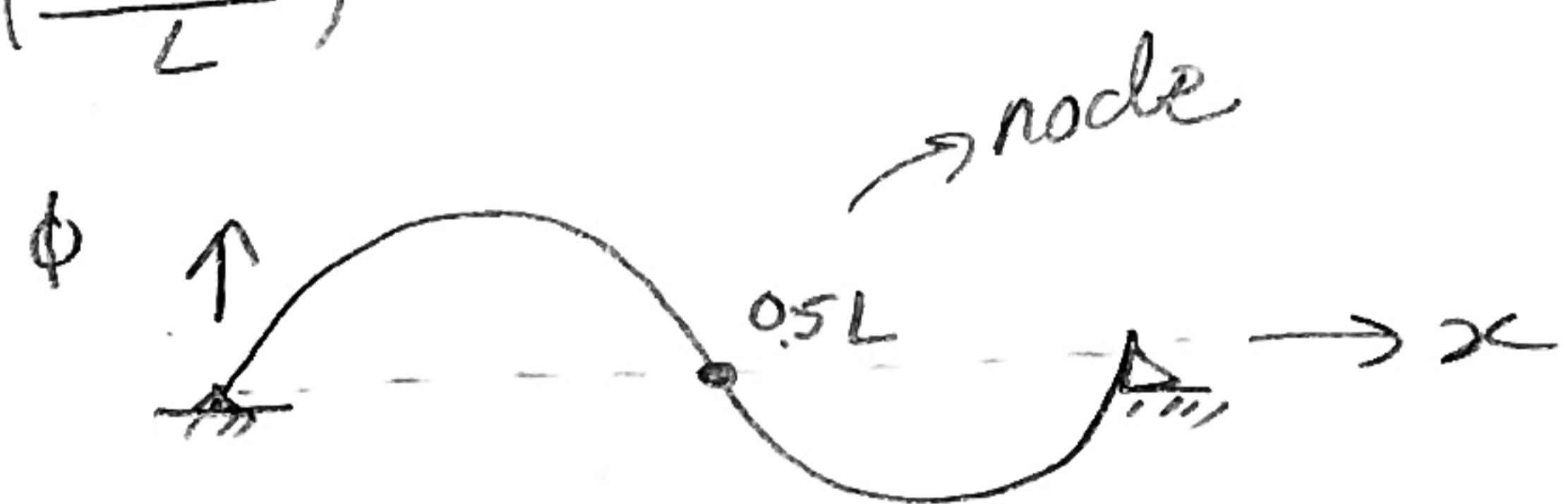
$$\phi_1(x) = \sin\left(\frac{\pi}{L}x\right)$$



$$\omega_1 = (\pi)^2 \sqrt{\frac{EI}{\rho A L^4}}$$

Second Mode shape $n=2$

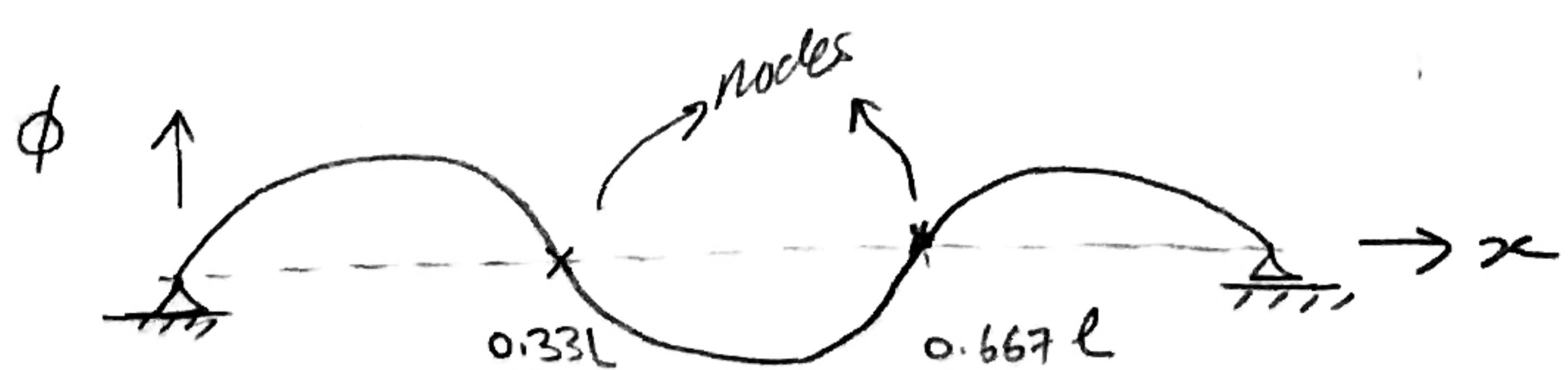
$$\phi_2(x) = \sin\left(\frac{2\pi}{L}x\right)$$



$$\omega_2 = (2\pi)^2 \sqrt{\frac{EI}{\rho A L^4}}$$

Third mode shape ($n=3$)

$$\phi_3(x) = \sin\left(\frac{3\pi}{L}x\right)$$



$$\omega_3 = (3\pi)^2 \sqrt{\frac{EI}{\rho A L^4}}$$

by-supported Beam, cont'd

Initial conditions

$$w(x, 0) = w_0 \quad (2)$$

$$\dot{w}(x, 0) = \dot{w}_0$$

$n \leftarrow$ number of modes

$$w(x, t) = \sum_{i=1}^n \phi_i \gamma_i(t), \quad \gamma_i(t) = A_i \cos \omega_i t + B_i \sin \omega_i t$$

$$\phi_i(x) = \sin \omega_i x$$

$$\omega_n = (n\pi) \sqrt{\frac{EI}{\rho A L^4}}$$

$$= \sum_{i=1}^n (\sin \omega_i x) (A_i \cos \omega_i t + B_i \sin \omega_i t)$$

$$w(x, 0) = w_0 = \sum_{i=1}^n (\sin \omega_i x) A_i \Rightarrow A_i = \frac{2}{L} \int_0^L w_0 \sin \frac{n\pi}{L} x dx$$

$$\dot{w}(x, t) = \sum_{i=1}^n (\omega_i) (\sin \omega_i x) [-A_i \sin \omega_i t + B_i \cos \omega_i t]$$

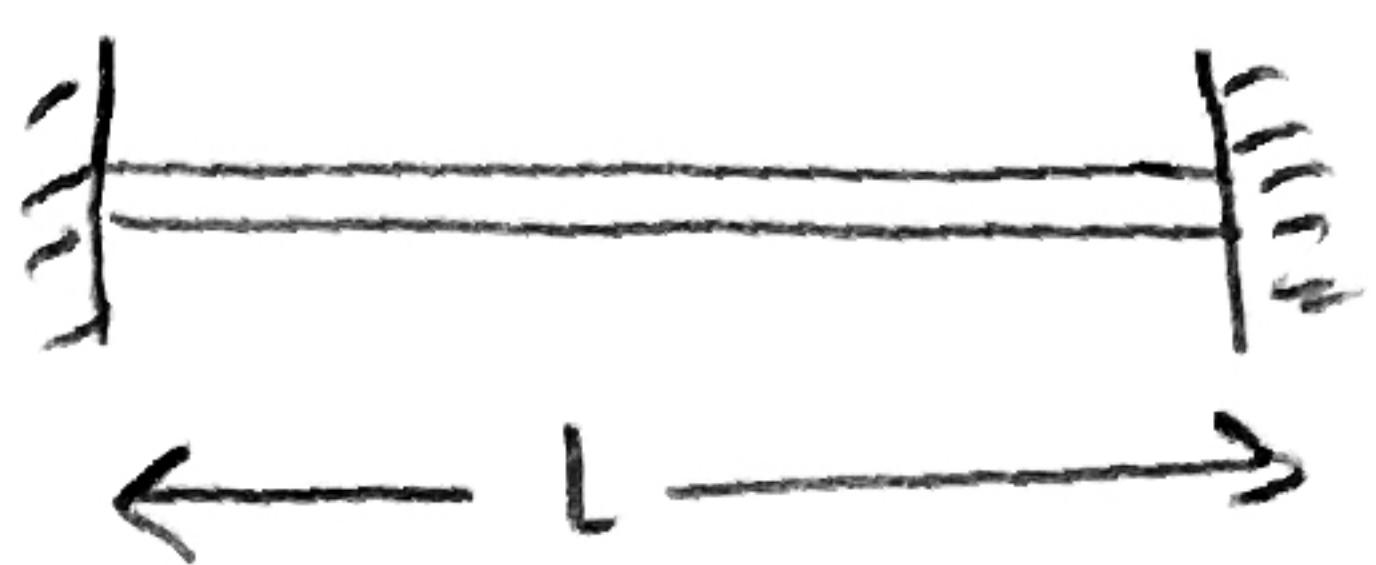
$$\dot{w}(x, 0) = \dot{w}_0 = \sum_{i=1}^n \omega_i \sin \omega_i x B_i \Rightarrow B_i = \frac{2}{\omega_i L} \int_0^L \dot{w}_0 \sin \frac{n\pi}{L} x dx$$

①

Natural Frequencies and mode shapes of Fixed-free Beam

EOM

$$EI \ddot{w}_{xxxx} + \rho A \ddot{w} = 0 \quad -(1)$$

BC's

$$w(0,t) = w(l,t) = 0$$

$$\dot{w}_x(0,t) = \dot{w}_x(l,t) = 0$$

Find Nat. Frag and mode shapes.

Solutionseparation of variables

$$w(x,t) = \phi(x)\gamma(t) \quad \text{Sub in eq(1)}$$

$$EI \ddot{\phi}_{xxxx} + \rho A \ddot{\phi} \gamma = 0$$

$$\frac{\ddot{\gamma}}{\gamma} = - \frac{C^2}{\frac{EI}{\rho A}} \cdot \frac{\ddot{\phi}_{xxxx}}{\phi} = -\omega^2$$

$$\ddot{\gamma} + \omega^2 \gamma = 0 \Rightarrow \gamma(t) = A \cos \omega t + B \sin \omega t$$

$$\ddot{\phi}_{xxxx} - \frac{(\omega)^2}{\frac{EI}{\rho A}} \phi_{xx} = 0 \Rightarrow \ddot{\phi}_{xxxx} - P^4 \phi = 0$$

$$\Rightarrow \omega^2 = P^2 \sqrt{\frac{EI}{\rho A}}$$

$$\phi(x) = a \cos px + b \sin px + c \cosh px + d \sinh px$$

Apply BC's

$$\phi(0) = 0 \Rightarrow a + c = 0$$

$$\phi_x(0) = 0 \Rightarrow \phi_x(x) = -pa \sin px + pb \cos px + pc \sinh px + pd \cosh px$$

$$\phi_x(0) = 0 \Rightarrow pb + pd = 0 \quad b + d = 0$$

(2)

fixed-fixed beam, cont'd

$$\phi(l) = 0 \Rightarrow a \cos p_l l + b \sin p_l l + c \cosh p_l l + d \sinh p_l l = 0$$

$$\begin{aligned} \phi_x(l) = 0 &\Rightarrow -\beta a \sin p_l l + \beta b \cos p_l l + \beta c \sinh p_l l + \beta d \cosh p_l l = 0 \\ &-a \sin p_l l + b \cos p_l l + c \sinh p_l l + d \cosh p_l l = 0 \end{aligned}$$

$$\left[\begin{array}{ccccc} 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \\ \cos p_l l & \sin p_l l & \cosh p_l l & \sinh p_l l \\ -\sin p_l l & \cos p_l l & \sinh p_l l & \cosh p_l l \end{array} \right] \left\{ \begin{array}{c} a \\ b \\ c \\ d \end{array} \right\} = \left\{ \begin{array}{c} 0 \\ 0 \\ 0 \\ 0 \end{array} \right\}$$

$\neq 0$

$\hookrightarrow \det[\] = 0$

If we set $\det[\] = 0 \Rightarrow \cos p_l l \cosh p_l l - 1 = 0$

$\hookrightarrow (p_l l)$ is root of this equation and
could be solved numerically
"Newton Raphson method"

$$\Rightarrow p_n = \frac{(2n+1)\pi}{2L}$$

$$w_n = p_n^2 \sqrt{\frac{EI}{PA}}$$

$$= \left[\frac{(2n+1)\pi}{2} \right]^2 \sqrt{\frac{EI}{PA L^4}}$$

\Rightarrow Assume $a = 1 \Rightarrow$ then we can find b, c and d

$$\Rightarrow \phi_n = [\cos p_n x + \cosh p_n x] - \frac{\cos p_n l - \cosh p_n l}{\sin p_n l - \sinh p_n l} [\sin p_n x + \sinh p_n x]$$

$$w(x,t) = \sum_{i=1}^n \phi_i(x) \gamma_i(t)$$

$$\gamma_n(t) = A_n \cos \omega_n t + B_n \sin \omega_n t$$