

Graduate QM

HW #2 - solution

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①

$$\begin{aligned}
 \textcircled{a} \quad & \left[l_i, \frac{p^2}{2m} \right] = \left[(r \times p)_i, \frac{p^2}{2m} \right] = \left[\epsilon_{ijk} x_j p_k, \frac{p^2}{2m} \right] \\
 &= \frac{\epsilon_{ijk}}{2m} \left[x_j p_k, p^2 \right] \\
 &= \frac{\epsilon_{ijk}}{2m} \left(x_j \left[p_k, p^2 \right]^0 + [x_j, p^2] p_k \right) \\
 &= \frac{\epsilon_{ijk}}{2m} \left[x_j, p_j^2 \right] p_k ; \text{ when } [x_j, p_i^2] = [x_j, p_k^2] = 0 \\
 &= \frac{\epsilon_{ijk}}{2m} i\hbar \frac{\partial p_j^2}{\partial p_i} p_k = \frac{\epsilon_{ijk}}{2m} i\hbar 2p_j p_k \\
 &= \frac{i\hbar}{m} \epsilon_{ijk} p_j p_k = \frac{i\hbar}{m} (p \times p)_i = 0 \quad \text{Q.E.D}
 \end{aligned}$$

where I used $(a \times b)_i = \epsilon_{ijk} a_j b_k$

$$\textcircled{b} \quad \text{Starting from } i\hbar \frac{d}{dt} \langle l_i \rangle = \langle [l_i, H] \rangle$$

$$\text{when } H = \frac{p^2}{2m} + V(\vec{r})$$

$$\begin{aligned}
 \Rightarrow i\hbar \frac{d}{dt} \langle l_i \rangle &= \langle \left[(r \times p)_i, \frac{p^2}{2m} + V(r^2) \right] \rangle = \langle \left[\epsilon_{ijk} x_j p_k, \frac{p^2}{2m} + V(r^2) \right] \rangle \\
 &= \epsilon_{ijk} \left\langle \left[x_j p_k, \frac{p^2}{2m} \right] + [x_j p_k, V(r^2)] \right\rangle
 \end{aligned}$$

$$\begin{aligned}
i\hbar \frac{d}{dt} \langle l_i \rangle &= \epsilon_{ijk} \left\langle \cancel{\frac{1}{2m} x_j [P_k, P^2]}^0 + \frac{1}{2m} [x_j, P^2] P_k \right. \\
&\quad \left. + x_j [P_k, V(\vec{r})] + [x_j, V(\vec{r})]^0 P_k \right\rangle \\
&= \epsilon_{ijk} \left\langle \frac{1}{2m} 2i\hbar P_j P_k + x_j \left(-i\hbar \frac{\partial V}{\partial x_k} \right) \right\rangle \\
&= \frac{1}{m} i\hbar \epsilon_{ijk} P_j P_k - \epsilon_{ijk} x_j i\hbar \partial_k V ; \text{ when } \frac{\partial V}{\partial x_k} = \partial_k V \\
&= \frac{1}{m} i\hbar \cancel{(P \times P)_i}^0 - i\hbar \epsilon_{ijk} x_j \partial_k V \\
&= -i\hbar \epsilon_{ijk} x_j \partial_k V = -i\hbar (\vec{r} \times \vec{\nabla} V)_i
\end{aligned}$$

$$\therefore \frac{d}{dt} \langle l_i \rangle = -(\vec{r} \times \vec{\nabla} V)_i$$

$$\Rightarrow \frac{d}{dt} \langle \vec{l} \rangle = -(\vec{r} \times \vec{\nabla} V) \quad \text{Q.E.D}$$

$$\begin{aligned}
\textcircled{C} \quad [l_i, f(P^2)] &= [(r \times P)_i, f(P^2)] = \{\epsilon_{ijk} x_j P_k, f(P^2)\} \\
&= \epsilon_{ijk} (x_j \cancel{[P_k, f(P^2)]}^0 + [x_j, f(P^2)] P_k) = \epsilon_{ijk} [x_j, f(P^2)] P_k \\
&= \epsilon_{ijk} i\hbar \frac{\partial f(P^2)}{\partial P_j} P_k = (\text{const}) i\hbar \epsilon_{ijk} P_j P_k \\
&= (\text{const}) i\hbar (P \times P)_i = 0
\end{aligned}$$

$$\Rightarrow \text{similarly } [l_i, f(P^2)] = [l_k, f(P^2)] = 0$$

$$\Rightarrow [\vec{l}, f(P^2)] = 0$$

$$\begin{aligned}
[\ell_i, f(r^i)] &= \{(\mathbf{r} \times \mathbf{p})_i, f(r^i)\} \\
&= \{\varepsilon_{ijk} x_j p_k, f(r^i)\} \\
&= \varepsilon_{ijk} \left(x_j \{p_k, f(r^i)\} + \overbrace{x_j / f(r^i)}^0 p_k \right) \\
&= \varepsilon_{ijk} x_j \{p_k, f(r^i)\} \\
&= \varepsilon_{ijk} x_j \{p_k, f(x_k^i)\} ; \text{ where } \\
&\quad \{p_k, f(x_i^i)\} = 0 \\
&= \varepsilon_{ijk} x_j \left(-i \hbar \frac{\partial f}{\partial x_k} \right) \\
&\quad \{p_k, f(x_j^i)\} = 0 \\
&= -i \hbar \varepsilon_{ijk} x_j \frac{\partial f}{\partial x_k} \\
&= (\text{const}) i \hbar \varepsilon_{ijk} x_j x_k \\
&= (\text{const}) i \hbar (\vec{r} \times \vec{r})_i = 0 \\
\text{similarly } [\ell_j, f(r^i)] &= \{\ell_k, f(r^i)\} = 0 \\
\Rightarrow [\vec{\ell}, f(r^i)] &= 0
\end{aligned}$$

CQ. E. D.

$$② \hat{D} \Psi(\vec{r}) = \Psi(\vec{r} - \vec{a})$$

a) under infinitesimal translation of $\delta\vec{a}$ we have

$$\Psi'(\vec{r}) = D \Psi(\vec{r}) = \Psi(\vec{r} - \delta\vec{a})$$

$$\begin{aligned} \text{now } \Psi(\vec{r} - \delta\vec{a}) &\approx \Psi(\vec{r}) - \delta\vec{a} \cdot \vec{\nabla} \Psi ; \text{ but } \vec{p} = -i\hbar \vec{\nabla} \\ &\approx \Psi(\vec{r}) - \frac{i}{\hbar} (\delta\vec{a} \cdot \vec{p}) \Psi(\vec{r}) \\ &\approx [1 - \frac{i}{\hbar} \delta\vec{a} \cdot \vec{p}] \Psi(\vec{r}) \end{aligned}$$

$$\therefore \hat{D} \Psi(\vec{r}) = \Psi(\vec{r} - \delta\vec{a}) = [1 - \frac{i}{\hbar} \delta\vec{a} \cdot \vec{p}] \Psi(\vec{r})$$

$\Rightarrow \boxed{\hat{D} \approx 1 - \frac{i}{\hbar} \delta\vec{a} \cdot \vec{p}}$; \hat{p} is the generator of translation

⑥ for finite translation of \vec{a} ; $\vec{a} = N \delta\vec{a}$; $N \rightarrow \infty$

$$\begin{aligned} \therefore \hat{D}(\vec{a}) &= \lim_{N \rightarrow \infty} \left(\hat{D}(\delta\vec{a}) \right)^N \\ &\approx \lim_{N \rightarrow \infty} \left[1 - \frac{i}{\hbar} \frac{\vec{a} \cdot \vec{p}}{N} \right]^N \approx \left[e^{-\frac{i}{\hbar} \frac{\vec{a} \cdot \vec{p}}{N}} \right]^N \approx e^{-\frac{i}{\hbar} \vec{a} \cdot \vec{p}} \end{aligned}$$

⑦ For H to have translational symmetry, it is required that $[H, P] = 0$. This requires that both kinetic energy and potential energy commute with it

$$\text{i.e. } [V(x), P] = i\hbar \frac{dV}{dx} = 0$$

$$[\frac{P^2}{2m}, P] = 0 \quad \text{by default}$$

$$\Rightarrow \frac{dV}{dx} = 0 \Rightarrow V(x) = \text{constant} \equiv V_0$$

(3) $e^{-i \frac{\alpha}{2} (\text{a.n})} = \sum_{k=0}^{\infty} \frac{(-i \frac{\alpha}{2} \text{a.n})^k}{k!}$; this can be decomposed into an even and an odd series

$$= \sum_{k=0}^{\infty} \frac{(-i)^{2k} \left(\frac{\alpha}{2}\right)^{2k}}{(2k)!} (\text{a.n})^{2k} + \sum_{k=0}^{\infty} \frac{(-i)^{2k+1} \left(\frac{\alpha}{2}\right)^{2k+1}}{(2k+1)!} (\text{a.n})^{2k+1}$$

Now $(-i)^{2k} = (-1)^{2k} (i)^{2k} = (i^2)^k = (-1)^k$

and $(-i)^{2k+1} = \underbrace{(-1)^{2k+1}}_{=} (i)^{2k+1} = (-1) (i)^{2k} (i) = (-1) (i^2)^k (i) = -i (-1)^k$

$$= \sum_{k=0}^{\infty} \frac{(-1)^k \left(\frac{\alpha}{2}\right)^{2k}}{(2k)!} (\text{a.n})^{2k} - i \sum_{k=0}^{\infty} \frac{(-1)^k \left(\frac{\alpha}{2}\right)^{2k+1}}{(2k+1)!} (\text{a.n})^{2k+1}$$

Now using $(\text{a.n})^n = \begin{cases} I, & \text{even } n \\ \text{a.n}, & \text{odd } n \end{cases}$

$$\Rightarrow (\text{a.n})^{2k} = I \quad \text{and} \quad (\text{a.n})^{2k+1} = \text{a.n}$$

$$= I \underbrace{\sum_{k=0}^{\infty} \frac{(-1)^k \left(\frac{\alpha}{2}\right)^{2k}}{(2k)!}}_{\cos \frac{\alpha}{2}} - i (\text{a.n}) \underbrace{\sum_{k=0}^{\infty} \frac{(-1)^k \left(\frac{\alpha}{2}\right)^{2k+1}}{(2k+1)!}}_{\sin \frac{\alpha}{2}}$$

$$= I \cos\left(\frac{\alpha}{2}\right) - i (\text{a.n}) \sin\left(\frac{\alpha}{2}\right)$$

where I is the identity matrix, and sometimes it is called α_0

$$④ x_i = \begin{pmatrix} e^{-i\phi/2} \cos \frac{\theta}{2} \\ e^{i\phi/2} \sin \frac{\theta}{2} \end{pmatrix}$$

a) for bhc eigenvalue $+\frac{k}{2}$; $x_f = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$

" " " " - $\frac{k}{2}$; $x_f = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$

$$P\left(+\frac{k}{2}\right) = \left| \langle x_f | x_i \rangle \right|^2 = \left| \langle (1 \ 0) \begin{pmatrix} e^{-i\phi/2} \cos \frac{\theta}{2} \\ e^{i\phi/2} \sin \frac{\theta}{2} \end{pmatrix} \rangle \right|^2$$

$$= \left| e^{-i\phi/2} \cos \frac{\theta}{2} \right|^2 = \cos^2 \frac{\theta}{2}$$

$$P\left(-\frac{k}{2}\right) = \left| \langle x_f | x_i \rangle \right|^2 = \left| \langle (0 \ 1) \begin{pmatrix} e^{-i\phi/2} \cos \frac{\theta}{2} \\ e^{i\phi/2} \sin \frac{\theta}{2} \end{pmatrix} \rangle \right|^2$$

$$= \left| e^{i\phi/2} \sin \frac{\theta}{2} \right|^2 = \sin^2 \frac{\theta}{2}$$

$$\text{Notice that } P\left(+\frac{k}{2}\right) + P\left(-\frac{k}{2}\right) = \cos^2 \frac{\theta}{2} + \sin^2 \frac{\theta}{2} = 1$$

$$⑤ \langle x_i | S_z | x_i \rangle = \begin{pmatrix} e^{i\phi/2} \cos \frac{\theta}{2} & e^{-i\phi/2} \sin \frac{\theta}{2} \end{pmatrix} \frac{k}{2} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} e^{-i\phi/2} \cos \frac{\theta}{2} \\ e^{i\phi/2} \sin \frac{\theta}{2} \end{pmatrix}$$

$$= \frac{k}{2} \left(\cos^2 \frac{\theta}{2} - \sin^2 \frac{\theta}{2} \right) = \frac{k}{2} \cos \theta$$

same result would be obtained if we use $\langle x_f | S_z | x_f \rangle$

$$⑥ \text{ if } \theta = 0 \Rightarrow P\left(+\frac{k}{2}\right) = 1; P\left(-\frac{k}{2}\right) = 0$$

bhc beam is polarized in the same direction of the polarizer

$$\langle S_z \rangle = \frac{k}{2} \text{ as expected.}$$

$$⑤ H = \frac{k^2 L_z^2}{2I} ; \quad L_z = -i \cdot \frac{\partial}{\partial \phi}$$

need to solve $H\Psi = E\Psi \Rightarrow -\frac{k^2}{2I} \frac{d^2\Psi}{d\phi^2} = E\Psi$

$$\Rightarrow \frac{d^2\Psi}{d\phi^2} + m^2\Psi = 0 ; \quad m^2 = \frac{2IE}{k^2}$$

$$\Psi_m(\phi) = A e^{im\phi} ; \text{ normalize } \int_{-\pi}^{\pi} |\Psi|^2 d\phi = 1$$

$$\Rightarrow \Psi_m(\phi) = \frac{1}{\sqrt{2\pi}} e^{im\phi} \quad A = \frac{1}{\sqrt{2\pi}}$$

but Ψ is periodic and single-valued

$$\Psi(\phi) = \Psi(\phi + 2\pi)$$

$$\Rightarrow e^{im\phi} = e^{im(\phi+2\pi)} = e^{im\phi} e^{im2\pi}$$

$$\Rightarrow e^{im2\pi} = 1 \Rightarrow \cos(2\pi m) = 1$$

$$\Rightarrow 2\pi m = 0, \pm 2\pi, \pm 4\pi, \dots$$

$$\Rightarrow m = 0, \pm 1, \pm 2, \dots$$

we see that each level (except $m=0$) is two-fold degenerate

⑥ show that $(\vec{a} \cdot \vec{a})(\vec{a} \cdot \vec{b}) = \sigma_0 (\vec{a} \cdot \vec{b}) + i \sigma \cdot (\vec{a} \times \vec{b})$
 where σ_0 is the identity matrix
 starting from the L.H.S., we have

$$(\vec{a} \cdot \vec{a})(\vec{a} \cdot \vec{b}) = \left(\sum_i \sigma_i a_i \right) \left(\sum_j \sigma_j b_j \right)$$

$$= \sum_{i,j} \sigma_i \sigma_j a_i b_j$$

now using $\sigma_i \sigma_j = \sigma_0 \delta_{ij} + i \sum_k \epsilon_{ijk} \sigma_k$, we have

$$(\vec{a} \cdot \vec{a})(\vec{a} \cdot \vec{b}) = \sum_{i,j} \left(\sigma_0 \delta_{ij} + i \sum_k \epsilon_{ijk} \sigma_k \right) a_i b_j$$

$$= \sum_{i,j} \delta_{ij} \sigma_0 a_i b_j + i \sum_k \sigma_k \sum_{i,j} \epsilon_{ijk} a_i b_j$$

$$= \sigma_0 \sum_i a_i b_i + i \sum_k \sigma_k (\vec{a} \times \vec{b})_k$$

$$= \sigma_0 (\vec{a} \cdot \vec{b}) + i \sigma \cdot (\vec{a} \times \vec{b})$$

Q.E.D

Notice that if $\vec{a} = \vec{b} = \vec{n}$ unit vector

$$\Rightarrow (\vec{a} \cdot \vec{n})^2 = \sigma_0 = I \text{ identity}$$